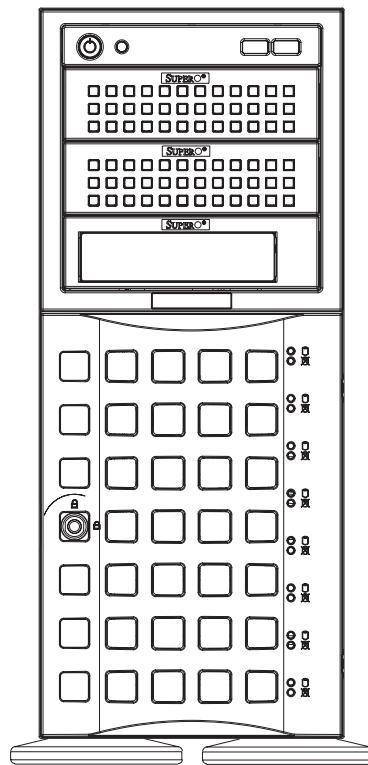


AS4021M-32R



USER'S MANUAL

1.0

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Manual Revision 1.0

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Preface

About This Manual

This manual is written for professional system integrators and PC technicians. It provides information for the installation and use of the 4021M-32R server. Installation and maintenance should be performed by experienced technicians only.

The 4021M-32R is a high-end server based on the SC745TQ-R800 tower/4U rackmount chassis and the H8DM3-2, a dual processor serverboard that supports AMD Opteron™ 2000 Series Socket F type processors and up to 32 GB of DDR2-667/533/400 registered ECC SDRAM.

Manual Organization

Chapter 1: Introduction

The first chapter provides a checklist of the main components included with the server system and describes the main features of the H8DM3-2 serverboard and the SC745TQ-R800chassis, which comprise the 4021M-32R .

Chapter 2: Server Installation

This chapter describes the steps necessary to install the 4021M-32R into a rack and check out the server configuration prior to powering up the system. If your server was ordered without processor and memory components, this chapter will refer you to the appropriate sections of the manual for their installation.

Chapter 3: System Interface

Refer here for details on the system interface, which includes the functions and information provided by the control panel on the chassis as well as other LEDs located throughout the system.

Chapter 4: System Safety

You should thoroughly familiarize yourself with this chapter for a general overview of safety precautions that should be followed when installing and servicing the 4021M-32R.

Chapter 5: Advanced Serverboard Setup

Chapter 5 provides detailed information on the H8DM3-2 serverboard, including the locations and functions of connections, headers and jumpers. Refer to this chapter when adding or removing processors or main memory and when reconfiguring the serverboard.

Chapter 6: Advanced Chassis Setup

Refer to Chapter 6 for detailed information on the SC745TQ-R800 server chassis. You should follow the procedures given in this chapter when installing, removing or reconfiguring SAS or peripheral drives and when replacing a system power supply or cooling fan.

Chapter 7: BIOS

The BIOS chapter includes an introduction to BIOS and provides detailed information on running the CMOS Setup Utility.

Appendix A: BIOS Error Beep Codes

Appendix B: BIOS POST Checkpoint Codes

Appendix C: System Specifications

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Appendix A: BIOS Error Beep Codes

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Appendix C: System Specifications

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Chapter 1

Introduction

1-1 Overview

The AS4021M-32R is a high-end server that is comprised of two main subsystems: the SC745TQ-R800 tower/4U server chassis and the H8DM3-2 dual AMD processor serverboard. Please refer to our web site for information on operating systems that have been certified for use with the 4021M-32R (www.supermicro.com).

In addition to the serverboard and chassis, various hardware components have been included with the 4021M-32R, as listed below:

- Three (3) 8-cm hot-swap chassis fans (FAN-0072L)
- Two (2) 8-cm hot-swap exhaust fans (FAN-0081L)
- One (1) air shroud (CSE-PT0123)
- Two (2) CPU passive heatsinks (SNK-P0023P)
- One (1) floppy disk drive, optional (FPD-PNSC-W1.44MB)
- Three (3) 4 to 3-pin fan cables (CBL-0209L)
- One (1) front control panel cable (CBL-0087)
- One (1) rackmount kit (CSE-PT26)
- SAS Accessories
 - One (1) SAS backplane (CSE-SAS-743TQ)
 - Two (2) iPass cables (CBL-0119L-02)
 - Eight (8) hot-swap hard drive carriers (CSE-PT17)*
- One (1) CD containing drivers and utilities

*The 4021M-32R is available in white and black; a "V" or a "03" following a part number indicates silver and a "B" or a "01" indicates black.

1-2 Serverboard Features

At the heart of the 4021M-32R lies the H8DM3-2, a dual processor serverboard based on the nVidia MCP55 Pro chipset and designed to provide maximum performance. Below are the main features of the H8DM3-2. (See Figure 1-1 for a block diagram of the MCP55 Pro chipset).

Processors

The H8DM3-2 supports single or dual AMD Opteron 2000 Series, Socket F type processors. Please refer to the serverboard description pages on our web site for a complete listing of supported processors (www.supermicro.com/aplus).

Memory

The H8DM3-2 has eight 240-pin DIMM slots that can support up to 32 GB of DDR2-667/533/400 registered ECC SDRAM. The memory operates in an interleaved configuration and requires modules of the same size and speed to be installed two at a time. See Chapter 5 Section 5 for details.

SAS

An LSI 1068E SAS controller is integrated into the H8DM3-2 to provide an eight-port SAS (Serial Attached SCSI) subsystem, which is RAID 0, 1, 10 and JBOD supported. (Optional RAID 5 support is available with the I-Button installed.) The SAS drives are hot-swappable units.

Note: The operating system you use must have RAID support to enable the hot-swap capability and RAID function of the SAS drives.

PCI Expansion Slots

The H8DM3-2 has six PCI expansion slots, which includes two PCI-Express x8 slots, one PCI-Express x4 slot, one 64-bit 133 MHz PCI-X slot and two 64-bit 133/100 MHz PCI-X slots.

Onboard Controllers/Ports

One floppy drive controller and one onboard ATA/133 controllers are provided to support up to two IDE hard drives or ATAPI devices. The color-coded I/O ports include one COM port (an additional COM header is located on the serverboard), a

VGA (monitor) port, two USB 2.0 ports, a parallel port, PS/2 mouse and keyboard ports and two gigabit Ethernet ports.

ATI Graphics Controller

The H8DM3-2 features an integrated ATI video controller based on the ES1000 graphics chip. The ES1000 was designed specifically for servers, featuring low power consumption, high reliability and superior longevity.

Other Features

Other onboard features that promote system health include onboard voltage monitors, a chassis intrusion header, auto-switching voltage regulators, chassis and CPU overheat sensors, virus protection and BIOS rescue.

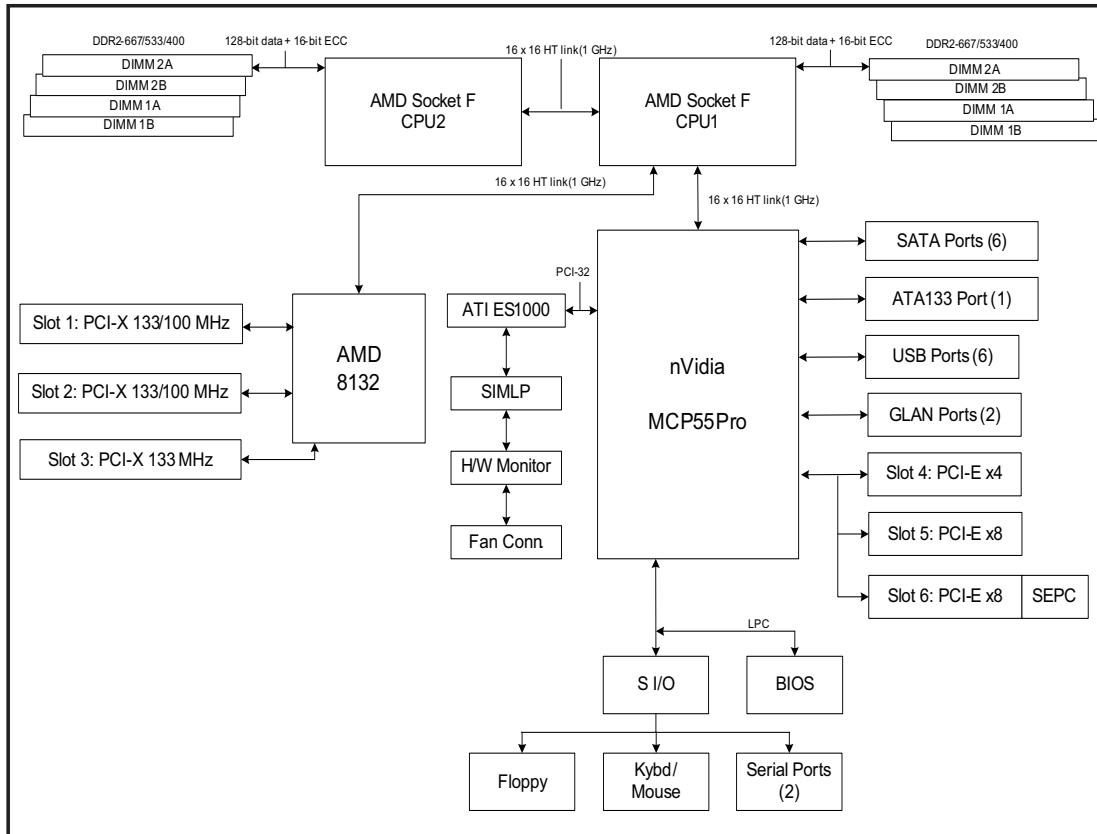


Figure 1-1. nVidia MCP55 Pro/AMD-8132 Chipset: System Block Diagram

Note: This is a general block diagram and may not exactly represent the features on your serverboard. See the previous pages for the actual specifications of your serverboard.

1-3 Server Chassis Features

The following is a general outline of the main features of the SC745TQ-R800 server chassis.

System Power

The SC745TQ-R800 features a redundant 800W power supply composed of two separate power modules. This power redundancy feature allows you to replace a failed power supply without shutting down the system.

SAS Subsystem

The SC745TQ-R800 chassis was designed to support eight SAS hard drives, which are hot-swappable units.

Note: The operating system you use must have RAID support to enable the hot-swap capability of the SAS drives.

Front Control Panel

The control panel on the AS4021M-32R provides you with system monitoring and control. LEDs indicate system power, HDD activity, network activity, system overheat and power supply failure. A main power button and a system reset button are also included. In addition, two USB ports have been incorporated into the control panel to provide front side USB access.

I/O Backplane

The SC745TQ-R800 is an ATX form factor chassis that may be used in either a tower or a 4U rackmount configuration. The I/O backplane provides six motherboard expansion slots, one COM port, a parallel port, a VGA port, two USB 2.0 ports, PS/2 mouse and keyboard ports and two gigabit Ethernet ports.

Cooling System

The SC745TQ-R800 chassis has an innovative cooling design that includes three 8-cm hot-plug system cooling fans located in the middle section of the chassis as well as two 8-cm hot-plug exhaust fans located at the rear of the chassis. An air shroud channels the airflow from the system fans to efficiently cool the processor area of the system. The power supply module also includes a cooling fan.

1-4 Contacting Supermicro

Headquarters

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Fax: +1 (408) 503-8008
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rma@supermicro.nl (Customer Support)

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Chung-Ho 235, Taipei, Taiwan, R.O.C.
Tel: +886-(2) 8226-3990
Fax: +886-(2) 8226-3991
Web Site: www.supermicro.com.tw

Technical Support:

Email: support@supermicro.com.tw
Tel: 886-2-8228-1366, ext.132 or 139

Notes

Chapter 2

Server Installation

2-1 Overview

This chapter provides a quick setup checklist to get your 4021M-32R up and running. Following these steps in the order given should enable you to have the system operational within a minimum amount of time. This quick setup assumes that your system has come to you with the processors and memory preinstalled. If your system is not already fully integrated with a serverboard, processors, system memory etc., please turn to the chapter or section noted in each step for details on installing specific components.

The 4021M-32R may be employed either as a tower or mounted in a rack as a 4U rackmount chassis. If using it as a tower unit, please read the Server Precautions in the next section and then skip ahead to Section 2-5.

2-2 Unpacking the System

You should inspect the box the system was shipped in and note if it was damaged in any way. If the server itself shows damage you should file a damage claim with the carrier who delivered it.

Decide on a suitable location for the 4021M-32R. It should be situated in a clean, dust-free area that is well ventilated. Avoid areas where heat, electrical noise and electromagnetic fields are generated. You will also need it placed near a grounded power outlet. Be sure to read the Rack and Server Precautions in the next section.

2-3 Preparing for Setup

The box the system was shipped in may include two sets of rail assemblies, two rail mounting brackets and mounting screws needed for installing the system into a rack (optional kit). Follow the steps in the order given to complete the installation process in a minimum amount of time. Please read this section in its entirety before you begin the installation procedure outlined in the sections that follow.

Choosing a Setup Location

- Leave enough clearance in front of the system to enable you to open the front door completely (~25 inches).
- Leave approximately 30 inches of clearance in the back of the system to allow for sufficient airflow and ease in servicing.
- This product is for installation only in a Restricted Access Location (dedicated equipment rooms, service closets and the like).
- This product is not suitable for use with visual display work place devices according to §2 of the German Ordinance for Work with Visual Display Units.



Warnings and Precautions!



Rack Precautions

- Ensure that the leveling jacks on the bottom of the rack are fully extended to the floor with the full weight of the rack resting on them.
- In single rack installation, stabilizers should be attached to the rack.
- In multiple rack installations, the racks should be coupled together.
- Always make sure the rack is stable before extending a component from the rack.
- You should extend only one component at a time - extending two or more simultaneously may cause the rack to become unstable.

Server Precautions

- Review the electrical and general safety precautions in Chapter 4.
- Determine the placement of each component in the rack *before* you install the rails.
- Install the heaviest server components on the bottom of the rack first, and then work up.
- Use a regulating uninterruptible power supply (UPS) to protect the server from power surges, voltage spikes and to keep your system operating in case of a power failure.
- Allow the hot plug SAS drives and power supply units to cool before touching them.
- Always keep the rack's front door and all panels and components on the servers closed when not servicing to maintain proper cooling.

Rack Mounting Considerations

Ambient Operating Temperature

If installed in a closed or multi-unit rack assembly, the ambient operating temperature of the rack environment may be greater than the ambient temperature of the room. Therefore, consideration should be given to installing the equipment in an environment compatible with the manufacturer's maximum rated ambient temperature (T_{mra}).

Reduced Airflow

Equipment should be mounted into a rack so that the amount of airflow required for safe operation is not compromised.

Mechanical Loading

Equipment should be mounted into a rack so that a hazardous condition does not arise due to uneven mechanical loading.

Circuit Overloading

Consideration should be given to the connection of the equipment to the power supply circuitry and the effect that any possible overloading of circuits might have on overcurrent protection and power supply wiring. Appropriate consideration of equipment nameplate ratings should be used when addressing this concern.

Reliable Ground

A reliable ground must be maintained at all times. To ensure this, the rack itself should be grounded. Particular attention should be given to power supply connections other than the direct connections to the branch circuit (i.e. the use of power strips, etc.).

2-4 Installing the System into a Rack

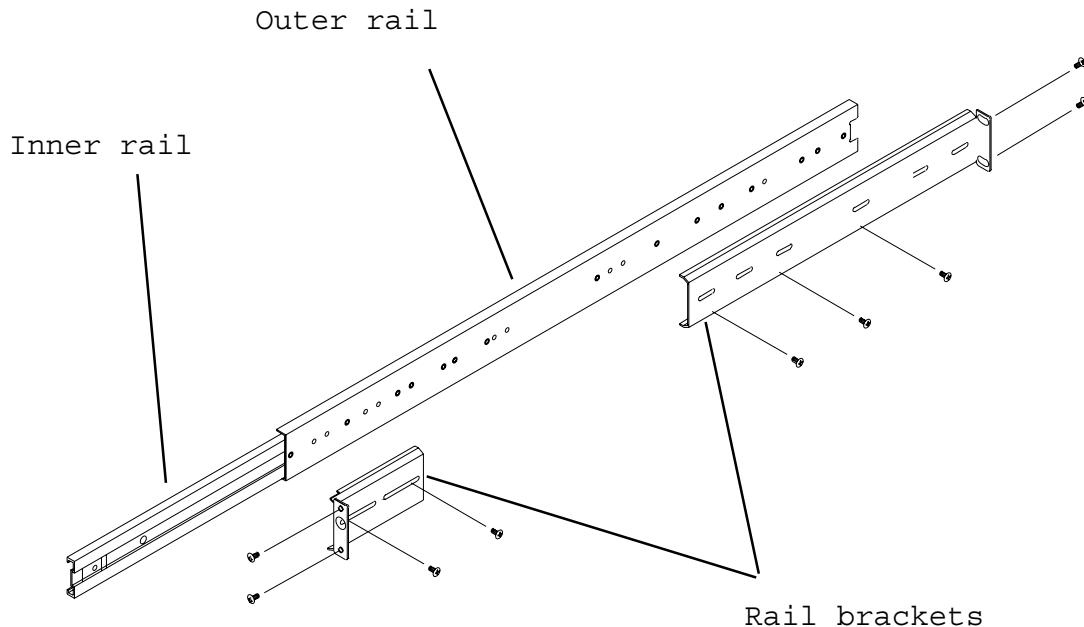
This section provides information on installing the system into a rack unit. Rack installation requires the use of the optional rackmount kit. If the system has already been mounted into a rack or if you are using it as a tower, you can skip ahead to Sections 2-5 and 2-6. There are a variety of rack units on the market, which may mean the assembly procedure will differ slightly. The following is a guideline for installing the server into a rack with the rack rails provided in the rackmount kit. You should also refer to the installation instructions that came with the rack unit you are using.

Identifying the Sections of the Rack Rails

The optional rackmount kit includes two rack rail assemblies. Each of these assemblies consist of three sections: an inner fixed chassis rail that secures to the chassis, an outer rack rail that secures directly to the rack itself and two rail brackets, which also attach to the rack (see Figure 2-1.) The inner and outer rails must be detached from each other to install.

To remove the inner chassis rail, pull it out as far as possible - you should hear a "click" sound as a locking tab emerges from inside the rail assembly and locks the inner rail. Depress the locking tab to pull the inner rail completely out. Do this for both assemblies (one for each side).

Figure 2-1. Identifying the Sections of the Rack Rails



Installing the Chassis Rails

You will need to remove the top cover and the feet to add rack rails to the chassis. First, remove the top and right covers (top and left covers when standing as a tower chassis) by first removing the screws that secure them to the chassis. Depress the button on the top (side if tower) of the chassis to release the cover and then pull the cover off. Then unscrew the four feet and remove them from the chassis (see Figure 2-2).

You can now attach rack rails to the top and bottom (now the sides) of the chassis. First add the rack handles. Then position the inner chassis rail sections you just removed along the side of the chassis making sure the screw holes line up. Note that these two rails are left/right specific. Screw the rail securely to the side of the chassis (see Figure 2-3). Repeat this procedure for the other rail on the other side of the chassis. You will also need to attach the rail brackets when installing into a telco rack.

Locking Tabs: As mentioned, the chassis rails have a locking tab, which serves two functions. The first is to lock the server into place when installed and pushed fully into the rack, which is its normal position. Secondly, these tabs also lock the server in place when fully extended from the rack. This prevents the server from coming completely out of the rack when you pull it out for servicing.

Figure 2-2. Preparing to Install the Chassis Rails

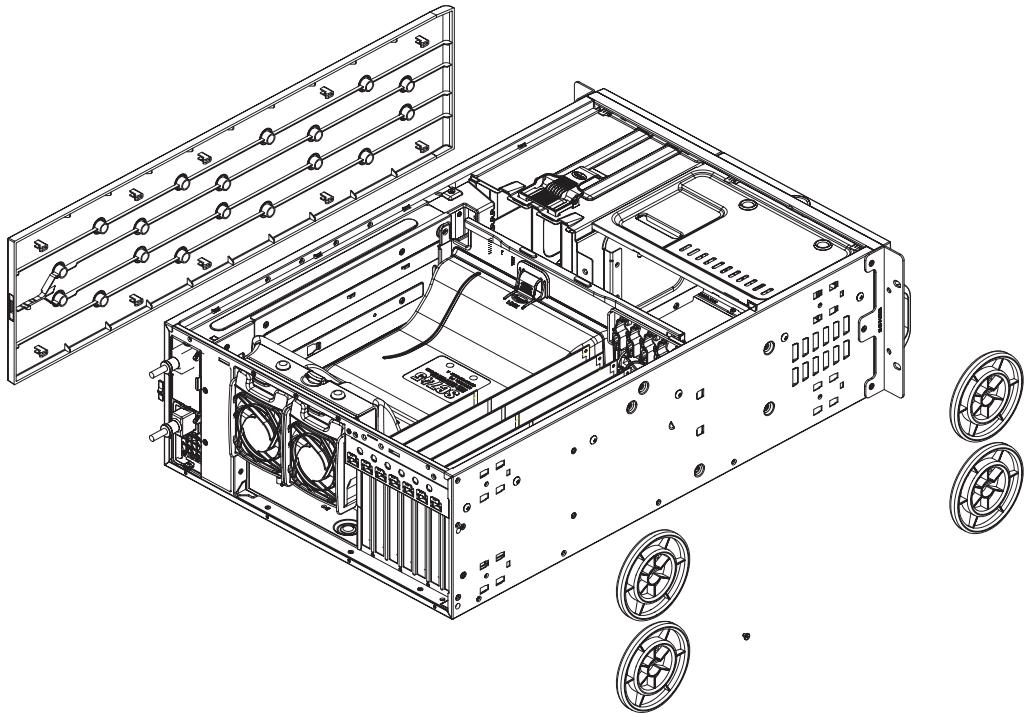
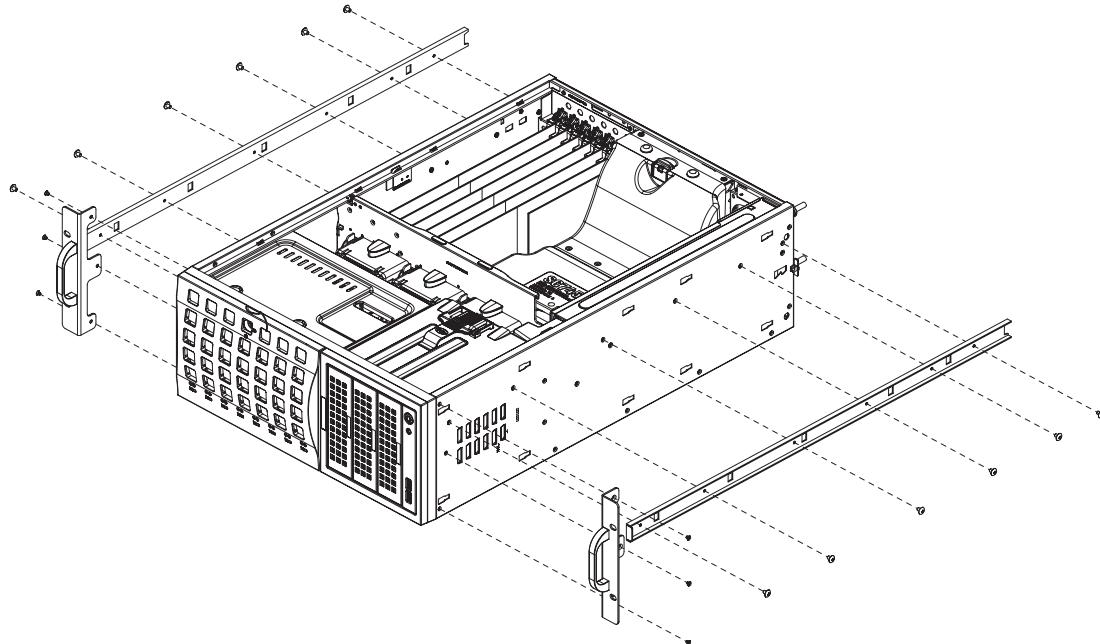


Figure 2-3. Installing the Rails to the Chassis

Installing the Rack Rails

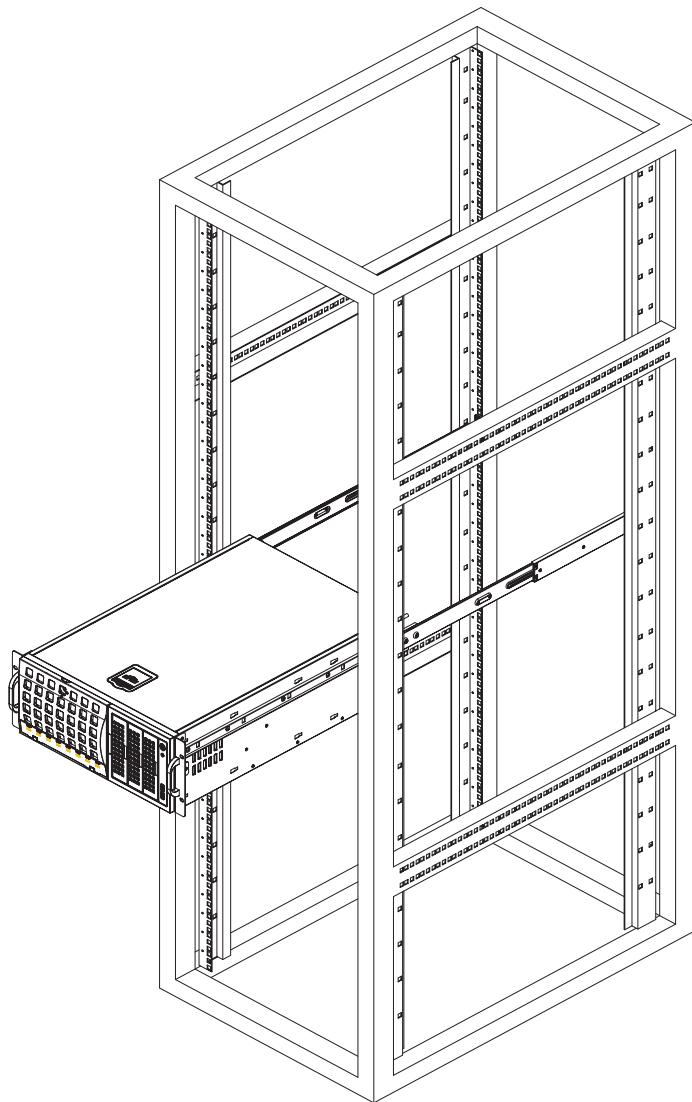
Determine where you want to place the SuperServer 4021M-32R in the rack. (See [Rack and Server Precautions in Section 2-3](#).) Position the fixed rack rail/sliding rail guide assemblies at the desired location in the rack, keeping the sliding rail guide facing the inside of the rack. Screw the assembly securely to the rack using the brackets provided. Attach the other assembly to the other side of the rack, making sure both are at the exact same height and with the rail guides facing inward.

Installing the Server into the Rack

You should now have rails attached to both the chassis and the rack unit. The next step is to install the server into the rack. You should have two brackets in the rack mount kit. Install these first keeping in mind that they are left/right specific (marked with "L" and "R"). Then, line up the rear of the chassis rails with the front of the rack rails. Slide the chassis rails into the rack rails, keeping the pressure even on both sides (you may have to depress the locking tabs when inserting).

When the server has been pushed completely into the rack, you should hear the locking tabs "click". Finish by inserting and tightening the thumbscrews that hold the front of the server to the rack (see Figure 2-4).

Figure 2-4. Installing the Server into a Rack



2-5 Checking the Serverboard Setup

After setting up the the system, you will need to open the unit to make sure the serverboard is properly installed and all the connections have been made.

1. Accessing the inside of the system (see Figure 2-5)

[If rack mounted, first release the retention screws that secure the unit to the rack. Grasp the two handles on either side and pull the unit straight out until it locks (you will hear a "click").] There are two screws that secure the cover to the chassis - remove these first. Locate the latch on the top (side if tower) of the chassis - depress where it says "push" then lift the latch to release the cover. You can then lift the cover from the chassis to gain full access to the inside of the server.

2. Check the CPUs (processors)

You may have one or two processors already installed into the serverboard. Each processor should have its own heatsink attached. See Chapter 5 for instructions on processor installation.

3. CPU clock ratio setting

The CPU speed should be automatically detected. No jumper or BIOS settings need to be made.

4. Check the system memory

Your server may have come with system memory already installed. Make sure all DIMMs are fully seated in their slots. For details on adding system memory, refer to Chapter 5.

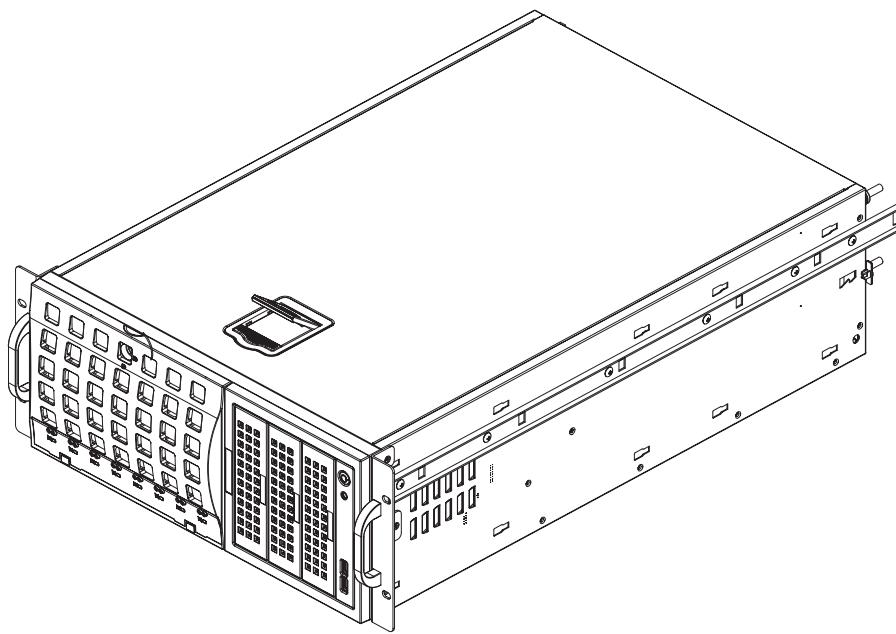
5. Installing add-on cards

If desired, you can install add-on cards to the system. See Chapter 5 for details on installing PCI add-on cards.

6. Check all cable connections and airflow

Make sure all power and data cables are properly connected and not blocking the chassis airflow. See Chapter 5 for details on cable connections.

**Figure 2-5. Accessing the Inside of the System
(Rack Configuration shown)**



2-6 Checking the Drive Bay Setup

Next, you should check to make sure the peripheral drives and the SAS drives and backplane have been properly installed and all connections have been made.

1. Accessing the drive bays

All drives can be accessed from the front of the server. For servicing the CD-ROM, IDE hard drives and floppy drives, you will need to remove the top/left chassis cover. The SAS disk drives can be installed and removed from the front of the chassis without removing any chassis covers.

2. Installing components into the 5.25" drive bays

To install components into the 5.25" drive bays, you must first remove the top/left chassis cover as described in the previous section. Refer to Chapter 6 for details.

3. Installing CD-ROM and floppy disk drives

Refer to Chapter 6 if you need to install a CD-ROM and/or floppy disk drive to the system.

4. Check the SAS disk drives

Depending upon your system's configuration, your system may have one or more drives already installed. If you need to install SAS drives, please refer to Chapter 6.

5. Check the airflow

Airflow is provided by three hot-swap 8-cm chassis fans working in conjunction with an air shroud. Two 8-cm exhaust fans are also mounted at the rear of the chassis. The system component layout was carefully designed to promote sufficient airflow through the chassis. Also note that all power and data cables have been routed in such a way that they do not block the airflow generated by the fans. Keep this in mind when you reroute them after working on the system.

6. Supplying power to the system

The last thing you must do is to provide input power to the system. Plug the power cords from the power supplies unit into a high-quality power strip that offers protection from electrical noise and power surges. It is recommended that you use an uninterruptible power supply (UPS). Finally, depress the power on button on the front of the chassis.

Chapter 3

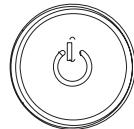
System Interface

3-1 Overview

The control panel on the 4021M-32R has several LEDs and two buttons. There are also two LEDs on each SAS drive carrier. These LEDs keep you constantly informed of the overall status of the system and the activity and health of specific components.

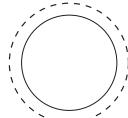
3-2 Control Panel Buttons

There are two push-buttons located on the front of the chassis: a power on/off button and a reset button.



- **POWER:** This is the main power button, which is used to apply or turn off the main system power. Turning off system power with this button removes the main power but keeps standby power supplied to the system.

RESET



- **RESET:** Use the reset button to reboot the system.

3-3 Control Panel LEDs

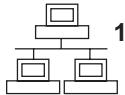
The control panel located on the front of the SC745TQ-R800 chassis has six LEDs that provide you with critical information related to different parts of the system. This section explains what each LED indicates when illuminated and any corrective action you may need to take.



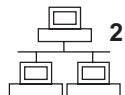
- **Power:** Indicates power is being supplied to the system's power supply. This LED should normally be on when the system is operating.



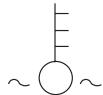
- **HDD:** Indicates IDE channel activity. On the 4021M-32R, this LED indicates SAS drive activity when flashing.



- **NIC1:** Indicates network activity on JLAN1 when flashing.



- **NIC2:** Indicates network activity on JLAN2 when flashing.



- **Overheat/Fan Fail:** When this LED flashes, it indicates a fan failure. When on continuously it indicates an overheat condition, which may be caused by cables obstructing the airflow in the system or the ambient room temperature being too warm. Check the routing of the cables and make sure all fans are present and operating normally. You should also check to make sure that the chassis covers are installed. Finally, verify that the heatsinks are installed properly (see Chapter 5). This LED will remain flashing or on as long as the indicated condition exists.



- **Power Fail:** Indicates a power supply module has failed. This should be accompanied by an audible alarm. A backup power supply module will take the load and keep the system running but the failed module will need to be replaced. Refer to Chapter 6 for details on replacing the power supply. This LED should be off when the system is operating normally.

3-4 SAS Drive Carrier LEDs

Each SAS drive carrier has two LEDs.

- **Green:** When illuminated, the green LED on the front of the SAS drive carrier indicates drive activity. A connection to the SAS backplane enables this LED to blink on and off when that particular drive is being accessed.
- **Red:** The SES2 backplane activates the red LED to indicate a drive failure. If one of the SAS drives fail, you should be notified by your system management software. Please refer to Chapter 6 for instructions on replacing failed SAS drives.

Notes

Chapter 4

System Safety

4-1 Electrical Safety Precautions



Basic electrical safety precautions should be followed to protect yourself from harm and the 4021M-32R from damage:

- Be aware of the locations of the power on/off switch on the chassis as well as the room's emergency power-off switch, disconnection switch or electrical outlet. If an electrical accident occurs, you can then quickly remove power from the system.
- Do not work alone when working with high voltage components.
- Power should always be disconnected from the system when removing or installing main system components, such as the serverboard, memory modules and the DVD-ROM and floppy drives. When disconnecting power, you should first power down the system with the operating system and then unplug the power cords of all the power supply units in the system.
- When working around exposed electrical circuits, another person who is familiar with the power-off controls should be nearby to switch off the power if necessary.
- Use only one hand when working with powered-on electrical equipment. This is to avoid making a complete circuit, which will cause electrical shock. Use extreme caution when using metal tools, which can easily damage any electrical components or circuit boards they come into contact with.
- Do not use mats designed to decrease electrostatic discharge as protection from electrical shock. Instead, use rubber mats that have been specifically designed as electrical insulators.

- The power supply power cord must include a grounding plug and must be plugged into grounded electrical outlets.
- Serverboard Battery: **CAUTION** - There is a danger of explosion if the onboard battery is installed upside down, which will reverse its polarities (see Figure 4-1). This battery must be replaced only with the same or an equivalent type recommended by the manufacturer. Dispose of used batteries according to the manufacturer's instructions.
- DVD-ROM Laser: **CAUTION** - this server may have come equipped with a DVD-ROM drive. To prevent direct exposure to the laser beam and hazardous radiation exposure, do not open the enclosure or use the unit in any unconventional way.

4-2 General Safety Precautions



Follow these rules to ensure general safety:

- Keep the area around the 4021M-32R clean and free of clutter.
- The 4021M-32R weighs approximately 64 lbs (29.1 kg.) when fully loaded. When lifting the system, two people at either end should lift slowly with their feet spread out to distribute the weight. Always keep your back straight and lift with your legs. Don't use the handles (if installed) to lift the chassis; the handles should only be used to pull the server out of the rack.
- Place the chassis top cover and any system components that have been removed away from the system or on a table so that they won't accidentally be stepped on.
- While working on the system, do not wear loose clothing such as neckties and unbuttoned shirt sleeves, which can come into contact with electrical circuits or be pulled into a cooling fan.
- Remove any jewelry or metal objects from your body, which are excellent metal conductors that can create short circuits and harm you if they come into contact with printed circuit boards or areas where power is present.

- After accessing the inside of the system, close the system back up and secure it to the rack unit with the retention screws after ensuring that all connections have been made.

4-3 ESD Precautions



Electrostatic discharge (ESD) is generated by two objects with different electrical charges coming into contact with each other. An electrical discharge is created to neutralize this difference, which can damage electronic components and printed circuit boards. The following measures are generally sufficient to neutralize this difference before contact is made to protect your equipment from ESD:

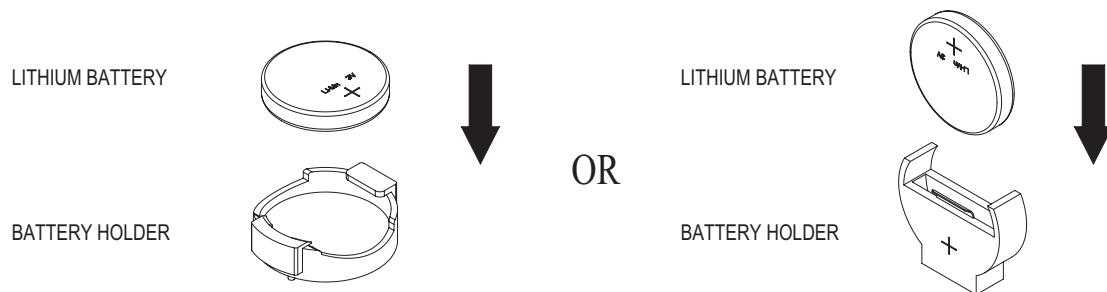
- Use a grounded wrist strap designed to prevent static discharge.
- Keep all components and printed circuit boards (PCBs) in their antistatic bags until ready for use.
- Touch a grounded metal object before removing the board from the antistatic bag.
- Do not let components or PCBs come into contact with your clothing, which may retain a charge even if you are wearing a wrist strap.
- Handle a board by its edges only; do not touch its components, peripheral chips, memory modules or contacts.
- When handling chips or modules, avoid touching their pins.
- Put the serverboard and peripherals back into their antistatic bags when not in use.
- For grounding purposes, make sure your computer chassis provides excellent conductivity between the power supply, the case, the mounting fasteners and the serverboard.

4-4 Operating Precautions



Care must be taken to assure that the chassis cover is in place when the 4021M-32R is operating to assure proper cooling. Out of warranty damage to the 4021M-32R system can occur if this practice is not strictly followed.

Figure 4-1. Installing the Onboard Battery



Chapter 5

Advanced Serverboard Setup

This chapter covers the steps required to install processors and heatsinks to the H8DM3-2 serverboard, connect the data and power cables and install add-on cards. All serverboard jumpers and connections are described and a layout and quick reference chart are included in this chapter. Remember to close the chassis completely when you have finished working on the serverboard to protect and cool the system sufficiently.

5-1 Handling the Serverboard

Static electrical discharge can damage electronic components. To prevent damage to printed circuit boards, it is important to handle them very carefully (see Chapter 4). Also note that the size and weight of the serverboard can cause it to bend if handled improperly, which may result in damage. To prevent the serverboard from bending, keep one hand under the center of the board to support it when handling. The following measures are generally sufficient to protect your equipment from static discharge.

Precautions

- Use a grounded wrist strap designed to prevent static discharge.
- Touch a grounded metal object before removing any board from its antistatic bag.
- Handle a board by its edges only; do not touch its components, peripheral chips, memory modules or gold contacts.
- When handling chips or modules, avoid touching their pins.
- Put the serverboard, add-on cards and peripherals back into their antistatic bags when not in use.

Unpacking

The serverboard is shipped in antistatic packaging to avoid static damage. When unpacking the board, make sure the person handling it is static protected.

5-2 Processor and Heatsink Installation



Exercise extreme caution when handling and installing the processor. Always connect the power cord last and always remove it before adding, removing or changing any hardware components.

Installing the CPU Backplates

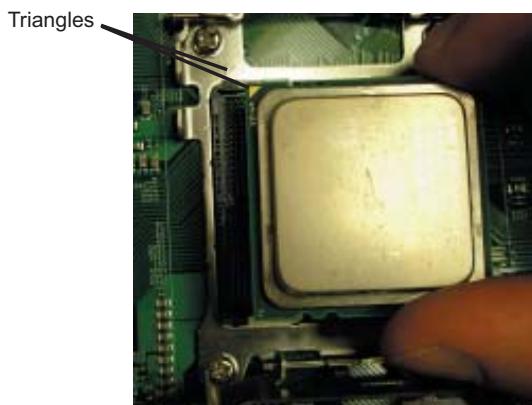
Two CPU backplates (BKT-0011L) have been preinstalled to the serverboard to prevent the CPU area of the serverboard from bending and to provide a base for attaching the heatsink retention modules.

Installing the Processor (install to the CPU#1 socket first)

1. Begin by removing the cover plate that protects the CPU. Lift the lever on CPU socket #1 until it points straight up. With the lever raised, lift open the silver CPU retention plate.



2. Use your thumb and your index finger to hold the CPU. Locate and align pin 1 of the CPU socket with pin 1 of the CPU. Both are marked with a triangle.



3. Align pin 1 of the CPU with pin 1 of the socket. Once aligned, carefully place the CPU into the socket. *Do not drop the CPU on the socket, move the CPU horizontally or vertically or rub the CPU against the socket or against any pins of the socket, which may damage the CPU and/or the socket.*



4. With the CPU inserted into the socket, inspect the four corners of the CPU to make sure that it is properly installed and flush with the socket. Then, gently lower the silver CPU retention plate into place.



5. Carefully press the CPU socket lever down until it locks into its retention tab. For a dual-processor system, repeat these steps to install another CPU into the CPU#2 socket.

Note: if using a single processor, only the CPU1 DIMM slots are addressable for a maximum of 16 GB memory.

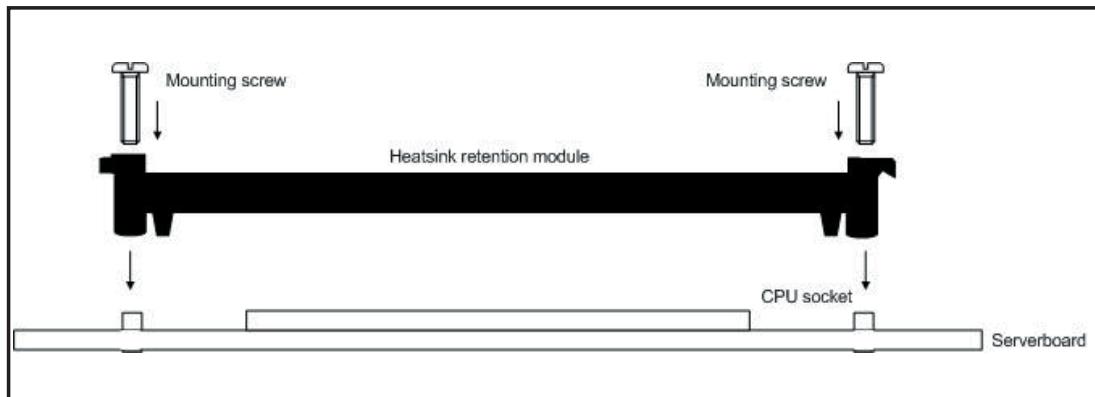


Installing the Heatsink Retention Modules

Two heatsink retention modules (BKT-0012L) and four screws are included in the retail box. Once installed, these are used to help attach the heatsinks to the CPUs. To install, align the module with the standoffs of the preinstalled CPU backplate and with the four feet on the module contacting the serverboard. Secure the retention module to the backplate with two of the screws provided. See Figure 2-1. Repeat for the second CPU socket.

Note: BKT-0012L is included for use with non-proprietary heatsinks only. When installing proprietary heatsinks, only BKT-0011L (the CPU backplate) is needed. The BKT-0012L retention module was designed to provide compatibility with clip-and-cam type heatsinks from third parties.

Figure 2-1. CPU Heatsink Retention Module Installation



Installing the Heatsink

The use of active type heatsinks (except for 1U systems) are recommended. Connect the heatsink fans to the appropriate fan headers on the serverboard. To install the heatsinks, please follow the installation instructions included with your heatsink package (not included).

5-3 Connecting Cables

Now that the processors are installed, the next step is to connect the cables to the serverboard. These include the data (ribbon) cables for the peripherals and control panel and the power cables.

Connecting Data Cables

The ribbon cables used to transfer data from the peripheral devices have been carefully routed in preconfigured systems to prevent them from blocking the flow of cooling air that moves through the system from front to back. If you need to disconnect any of these cables, you should take care to reroute them as they were originally after reconnecting them (make sure the red wires connect to the pin 1 locations). If you are configuring the system, keep the airflow in mind when routing the cables. The following data cables (with their serverboard connector locations noted) should be connected. See the serverboard layout diagram in this chapter for connector locations.

- DVD-ROM drive cable (IDE#1)
- SAS cables (SAS0 ~ SAS7)
- Control Panel cable (JF1, see next page)

Connecting Power Cables

The H8DM3-2 has a 24-pin primary power supply connector designated "J1B1" for connection to the ATX power supply. Connect the appropriate connector from the power supply to the "ATX Power" connector to supply power to the serverboard. See the Connector Definitions section in this chapter for power connector pin definitions.

In addition, your power supply must be connected to the 8-pin Processor Power connector at JPW1 and the 4-pin Auxiliary Power connector at JPW2.

Connecting the Control Panel

JF1 contains header pins for various front control panel connectors. See Figure 5-3 for the pin locations of the various front control panel buttons and LED indicators. Please note that even and odd numbered pins are on opposite sides of each header.

All JF1 wires have been bundled into single keyed ribbon cable to simplify their connection. The red wire in the ribbon cable plugs into pin 1 of JF1. Connect the other end of the cable to the Control Panel printed circuit board, located just behind the system status LEDs in the chassis.

See the Connector Definitions section in this chapter for details and pin descriptions of JF1.

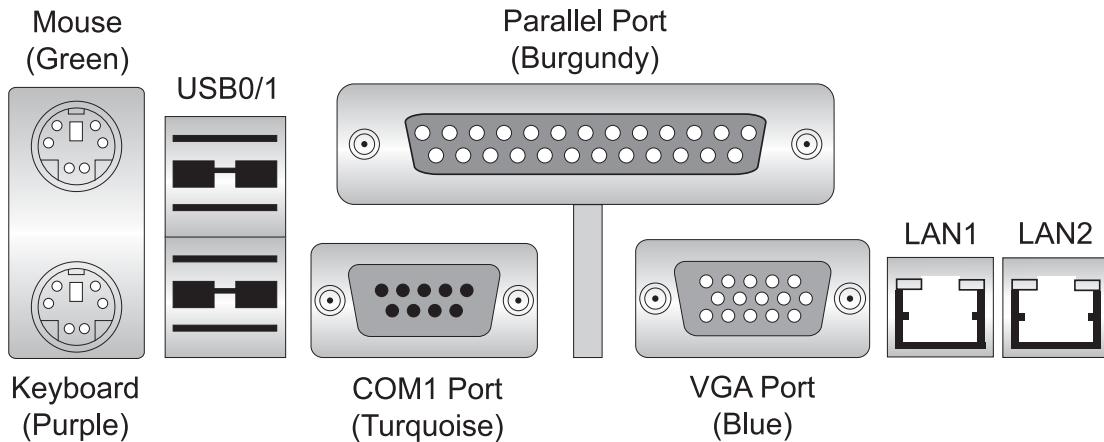
Figure 5-3. Front Control Panel Header Pins (JF1)

	20	19	
Ground	●	●	NMI
x (key)	●	●	x (key)
Power LED	●	●	Vcc
HDD LED	●	●	Vcc
NIC1	●	●	Vcc
NIC2	●	●	Vcc
OH/Fan Fail LED	●	●	Vcc
Power Fail LED	●	●	Vcc
Ground	●	●	Reset
Ground	●	●	Power
	2	1	

5-4 I/O Ports

The I/O ports are color coded in conformance with the PC 99 specification. See Figure 5-4 below for the colors and locations of the various I/O ports.

Figure 5-4. Rear Panel I/O Ports



5-5 Installing Memory

Note: Check the Supermicro web site for recommended memory modules.

CAUTION!

Exercise extreme care when installing or removing DIMM modules to prevent any possible damage. Also note that the memory is interleaved to improve performance (see step 1).

1. Insert each memory module vertically into its slot, paying attention to the notch along the bottom of the module to prevent inserting the module incorrectly (see Figure 5-5). See support information below.
2. Gently press down on the memory module until it snaps into place.

Note: each processor has its own built-in memory controller, so the CPU2 DIMMs cannot be addressed if only a single CPU is installed. 256 MB, 512 MB, 1 GB, 2 GB and 4 GB memory modules are supported. It is highly recommended that you remove the power cord from the system before installing or changing DIMMs.

Support

The H8DM3-2 supports single or dual-channel, DDR2-667/533/400 registered ECC SDRAM.

Both interleaved and non-interleaved memory are supported, so you may populate any number of DIMM slots (see note on previous page and charts on following page). The CPU2 DIMM slots can only be accessed when two CPUs are installed (however, the CPU2 DIMM slots are not required to be populated when two CPUs are installed).

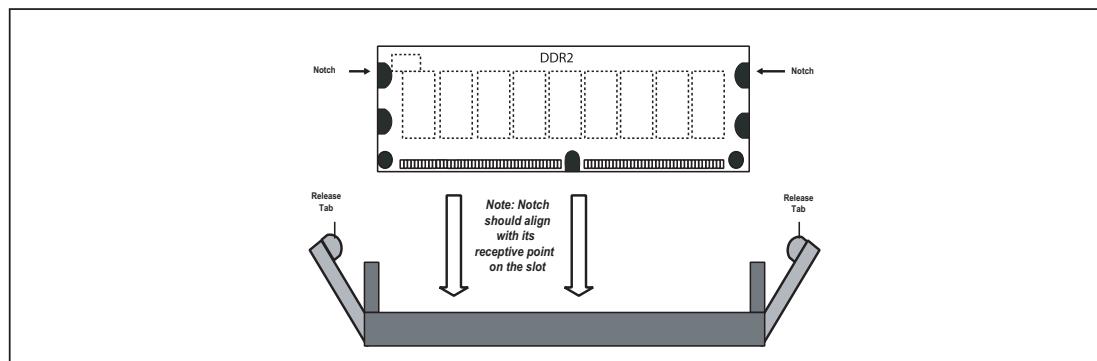
Populating two adjacent slots at a time with memory modules of the same size and type will result in interleaved (128-bit) memory, which is faster than non-interleaved (64-bit) memory. See charts on following page.

Optimizing memory performance

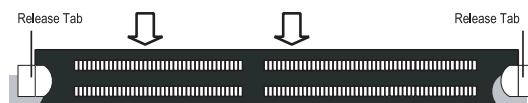
If two processors are installed, it is better to stagger pairs of DIMMs across both sets of CPU DIMM slots, e.g. first populate CPU1 slots 1A and 1B, then CPU2 slots 1A, and 1B, then the next two CPU1 slots, etc. This balances the load over both CPUs to optimize performance.

Maximum memory: 32 GB of registered ECC DDR2-667/533/400. If only one CPU is installed, maximum supported memory is halved.

Figure 5-5. Installing DIMM into Slot



Top View of DDR2 Slot



To Install: Insert module vertically and press down until it snaps into place. Pay attention to the bottom notches.

To Remove: Use your thumbs to gently push each release tab outward to free the DIMM from the slot.

Populating Memory Banks for 128-bit Operation							
CPU1 DIMM1A	CPU1 DIMM1B	CPU1 DIMM2A	CPU1 DIMM2B	CPU2 DIMM1A	CPU2 DIMM1B	CPU2 DIMM2A	CPU2 DIMM2B
X	X						
X	X			X	X		
X	X					X	X
X	X			X	X	X	X
X	X	X	X				
X	X	X	X	X	X		
X	X	X	X			X	X
X	X	X	X	X	X	X	X
		X	X				
		X	X	X	X		
		X	X			X	X
		X	X	X	X	X	X

Notes: X indicates a populated DIMM slot. If adding at least four DIMMs (with two CPUs installed), the configurations with DIMMs spread over both CPUs (and not like the configuration in row 5) will result in optimized performance. Note that the first two DIMMs must be installed in the CPU1 memory slots.

Populating Memory Banks for 64-bit Operation							
CPU1 DIMM1A	CPU1 DIMM1B	CPU1 DIMM2A	CPU1 DIMM2B	CPU2 DIMM1A	CPU2 DIMM1B	CPU2 DIMM2A	CPU2 DIMM2B
X							
		X					
X		X					
X				X			
X						X	
		X		X			
		X				X	

5-6 Adding PCI Cards

1. PCI slots

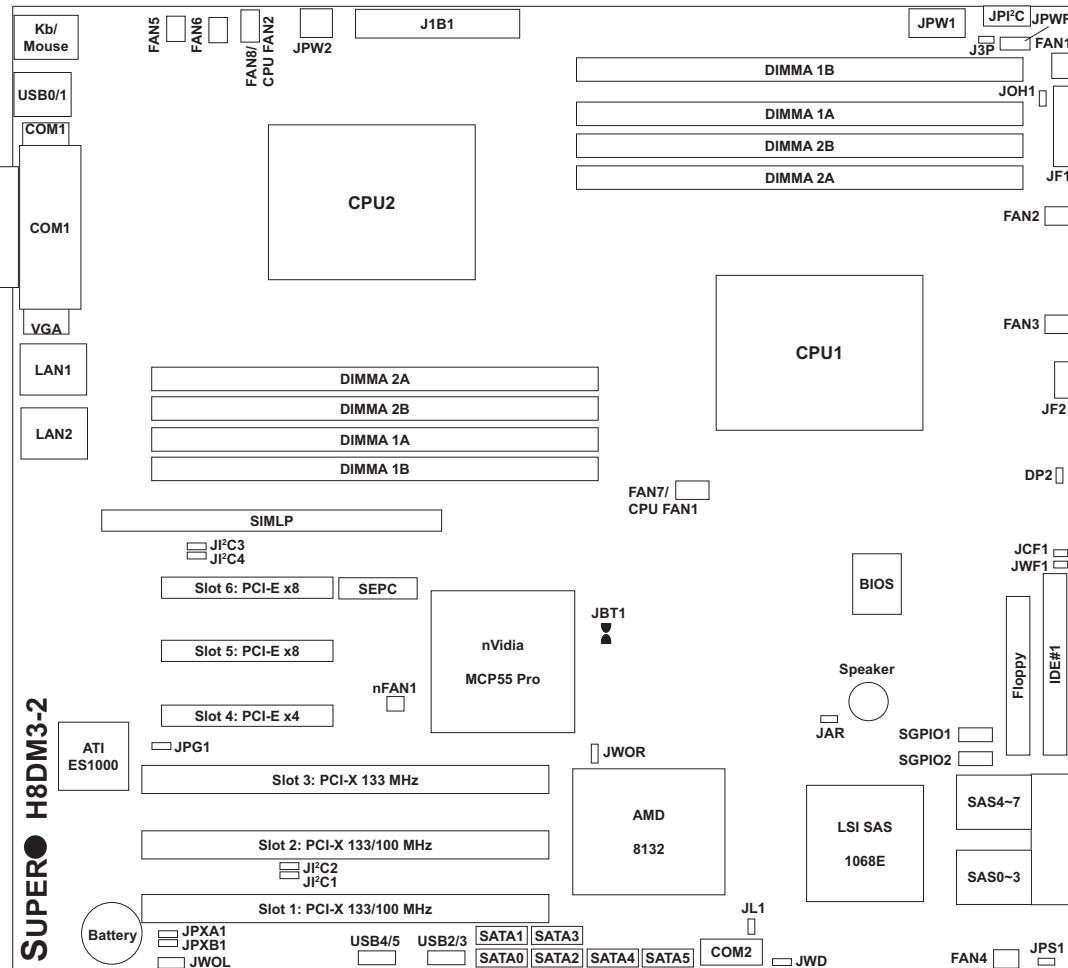
The H8DM3-2 has six PCI expansion slots, which includes two PCI-Express x8 slots, one PCI-Express x4 slot, one 64-bit 133 MHz PCI-X slot and two 64-bit 133/100 MHz PCI-X slots. The 4021M-32R can support cards in all six slots of the serverboard.

2. PCI card installation

Before installing a PCI add-on card, make sure you install it into a slot that supports the speed of the card (see step 1, above). After gaining access to the inside of the server, determine which slot you wish to populate, then press down on the curved section at the top of the blue tab for that slot. While pressing down, lift the tab to unlock the shield. Insert the expansion card into the correct slot on the serverboard, pushing down with your thumbs evenly on both sides of the card. Lock the card into place by pressing down on the tab. Follow this procedure when adding a card to other slots.

5-7 Serverboard Details

Figure 5-6. H8DM3-2 Serverboard Layout
(not drawn to scale)



Notes:

1. Jumpers not indicated are for test purposes only.
2. See the LSI SAS manual (included on the Supermicro CD) for SAS RAID set up instructions.

H8DM3-2 Quick Reference

Jumpers	Description	Default Setting
J3P	Power Supply Fail Detect	Closed (Enabled)
GBT1	CMOS Clear	See Section 5-9
JCF1	Compact Flash Master/Slave	Closed (Master)
JI ² C1/2	I ² C to PCI-X Enable/Disable	Pins 2-3 (Disabled)
JI ² C3/4	I ² C to PCI-E Enable/Disable	Pins 2-3 (Disabled)
JP1	VGA Enable/Disable	Pins 1-2 (Enabled)
JPS1	SAS RAID Select	Closed (SR RAID)
JPXA1/JPXB1	PCI-X Slot 1&2 Freq.	Open (Auto)
JWD	Watch Dog	Pins 1-2 (Reset)

Connectors	Description
COM1, COM2	COM1/COM2 Serial Port/Header
FAN 1-8	System Fan Headers
Floppy	Floppy Disk Drive Connector
IDE#1	IDE Drive Connector
J1B1	24-Pin ATX Power Connector
JAR	Power Fail Alarm Reset Header
JF1	Front Panel Connector
JF2	Onboard Speaker/Keylock/Power LED
JL1	Chassis Intrusion Header
JOH1	Overheat Warning Header
JPI ² C	Power Supply I ² C Header
JPW1	8-Pin Processor Power Connector
JPW2	4-pin Auxiliary Power Connector
JPWF	Power Supply Fail Alarm Header
JWF1	Compact Flash Card Power Connector
JWOL	Wake-On-LAN Header
JWOR	Wake-On-Ring Header
LAN1/2	Gigabit Ethernet (RJ45) Ports
nFAN1	Chipset Heatsink Fan Header
SAS0~3, SAS4~7	SAS Ports
SATA0 ~ SATA5	Serial ATA Ports
GPIO1/GPIO2	GPIO Headers
SIMLP	IPMI 2.0 Card Slot
USB0/1	Universal Serial Bus (USB) Ports 0/1
USB2/3, USB4/5	USB Headers

Indicators	Description
DP2	Onboard +5V Power LED

5-8 Connector Definitions

ATX Power Connector

The primary ATX power supply connector (J1B1) meets the SSI (Superset ATX) 24-pin specification. Refer to the table on the right for the pin definitions of the ATX 24-pin power connector. This connection supplies power to the chipset, fans and memory.

Note: You must also connect the 8-pin (JPW1) and 4-pin (JPW2) power connectors to your power supply (see below).

ATX Power 24-pin Connector Pin Definitions (J1B1)			
Pin#	Definition	Pin #	Definition
13	+3.3V	1	+3.3V
14	-12V	2	+3.3V
15	COM	3	COM
16	PS_ON	4	+5V
17	COM	5	COM
18	COM	6	+5V
19	COM	7	COM
20	Res (NC)	8	PWR_OK
21	+5V	9	5VSB
22	+5V	10	+12V
23	+5V	11	+12V
24	COM	12	+3.3V

Processor Power Connector

In addition to the primary ATX power connector (above), the 12v, 8-pin processor power connector at JPW1 must also be connected to your power supply. This connection supplies power to the CPUs. See the table on the right for pin definitions.

Processor Power Connector Pin Definitions (JPW1)	
Pins	Definition
1 through 4	Ground
5 through 8	+12V

Required Connection

Auxiliary Power Connector

The 4-pin auxiliary power connector at JPW2 must also be connected to your power supply. This connection supplies extra power that may be needed for high loads. See the table on the right for pin definitions.

Auxiliary Power Connector Pin Definitions (JPW2)	
Pins	Definition
1 & 2	Ground
3 & 4	+12V

Required Connection

Power LED

The Power LED connection is located on pins 15 and 16 of JF1. Refer to the table on the right for pin definitions.

Power LED Pin Definitions (JF1)	
Pin#	Definition
15	Vcc
16	Control

HDD LED

The HDD (IDE Hard Disk Drive) LED connection is located on pins 13 and 14 of JF1. Attach the IDE hard drive LED cable to display disk activity. Refer to the table on the right for pin definitions.

HDD LED Pin Definitions (JF1)	
Pin#	Definition
13	Vcc
14	HD Active

NIC1 LED

The NIC1 (Network Interface Controller) LED connection is located on pins 11 and 12 of JF1. Attach the NIC1 LED cable to display network activity. Refer to the table on the right for pin definitions.

NIC1 LED Pin Definitions (JF1)	
Pin#	Definition
11	Vcc
12	NIC1 Active

NIC2 LED

The NIC2 (Network Interface Controller) LED connection is located on pins 9 and 10 of JF1. Attach the NIC2 LED cable to display network activity. Refer to the table on the right for pin definitions.

NIC2 LED Pin Definitions (JF1)	
Pin#	Definition
9	Vcc
10	NIC2 Active

Overheat/Fan Fail LED

Connect an LED to the OH connection on pins 7 and 8 of JF1 to provide advanced warning of chassis overheating. Refer to the table on the right for pin definitions and status indicators.

OH/Fan Fail LED Pin Definitions (JF1)		OH/Fan Fail LED Status	
Pin#	Definition	State	Indication
7	Vcc	Solid	Overheat
8	Control	Blinking	Fan fail

Power Fail LED

The Power Fail LED connection is located on pins 5 and 6 of JF1. Refer to the table on the right for pin definitions. This feature is only available for systems with redundant power supplies.

Power Fail LED Pin Definitions (JF1)	
Pin#	Definition
5	Vcc
6	Control

Reset Button

The Reset Button connection is located on pins 3 and 4 of JF1. Attach it to the hardware reset switch on the computer case. Refer to the table on the right for pin definitions.

Reset Button Pin Definitions (JF1)	
Pin#	Definition
3	Reset
4	Ground

Power Button

The Power Button connection is located on pins 1 and 2 of JF1. Momentarily contacting both pins will power on/off the system. This button can also be configured to function as a suspend button (see the Power Button Mode setting in BIOS). To turn off the power when set to suspend mode, depress the button for at least 4 seconds. Refer to the table on the right for pin definitions.

Power Button Pin Definitions (JF1)	
Pin#	Definition
1	PW_ON
2	Ground

Universal Serial Bus Ports (USB0/1)

Two Universal Serial Bus ports (USB2.0) are located beside the LAN1/2 ports. See the table on the right for pin definitions.

Universal Serial Bus Ports Pin Definitions (USB0/1)			
USB0		USB1	
Pin #	Definition	Pin #	Definition
1	+5V	1	+5V
2	PO-	2	PO-
3	PO+	3	PO+
4	Ground	4	Ground

USB Headers

Four additional USB2.0 headers (USB2/3 and USB4/5) are included on the serverboard. These may be connected to provide front side access. A USB cable (not included) is needed for the connection. See the table on the right for pin definitions.

Universal Serial Bus Headers Pin Definitions (USB2/3/4/5)				
USB2		USB3/4		
Pin #	Definition	Pin #	Definition	
1	+5V	1	+5V	
2	PO-	2	PO-	
3	PO+	3	PO+	
4	Ground	4	Ground	
5	Key	5	No connection	

ATX PS/2 Keyboard and PS/2 Mouse Ports

The ATX PS/2 keyboard and the PS/2 mouse ports are located on the IO backplane. The mouse is the top (green) port. See the table on the right for pin definitions.

PS/2 Keyboard and Mouse Port Pin Definitions	
Pin#	Definition
1	Data
2	NC
3	Ground
4	VCC
5	Clock
6	NC

Serial Ports

The COM1 port is located under the parallel port. COM2 is a header located beside the SATA5 port. See the serverboard layout for locations and the table on the right for pin definitions.

Serial Port Pin Definitions (COM1/COM2)			
Pin #	Definition	Pin #	Definition
1	DCD	6	DSR
2	RXD	7	RTS
3	TXD	8	CTS
4	DTR	9	RI
5	Ground	10	NC

Note: NC indicates no connection.

Fan Headers

The H8DM3-2 has eight fan headers, which are designated FAN1 through FAN8. FAN7 and FAN8 are for 4-pin Pulse Width Modulated (PWM) fans and are to be connected to the CPU heatsink fans. Their speed is controlled via Thermal Management with a BIOS setting. FAN1 through FAN6 are 3-pin, non-PWM fans. See the tables on the right for pin definitions.

4-pin Fan Header Pin Definitions (FAN7/FAN8)	
Pin#	Definition
1	Ground (Black)
2	+12V (Red)
3	Tachometer
4	PWM Control

Note: The nFAN1 header connects to the heatsink fan on the nVidia MCP 55 Pro chip. Do not disconnect this fan or the chipset may overheat. See the table on the right for pin definitions.

3-pin Fan Header Pin Definitions (FAN1-FAN6)	
Pin#	Definition
1	Ground (Black)
2	+12V (Red)
3	Tachometer

Power LED/Speaker/Keylock

On JF2, pins 2, 4, and 6 are for the power LED, pins 1, 3, 5 and 7 are for the speaker and pins 8 and 10 are for the keylock. See the tables on the right for pin definitions.

Note: The speaker connector pins are for use with an external speaker. If you wish to use the onboard speaker, you should close pins 5 and 7 with a jumper. Utilizing the keylock header allows you to inhibit any actions made on the keyboard, effectively "locking" it.

PWR LED Connector Pin Definitions (JF2)	
Pin#	Definition
2	+Vcc
4	Control
6	Control

Speaker Connector Pin Definitions (JF2)	
Pin#	Definition
1	Red wire, +5V
3	No connection
5	Buzzer signal
7	Speaker data

Overheat LED

Connect an LED to the JOH1 header to provide warning of chassis overheating. See the table on the right for pin definitions.

Overheat LED Pin Definitions (JOH1)	
Pin#	Definition
1	3.3V
2	OH Active

Chassis Intrusion

A Chassis Intrusion header is located at JL1. Attach the appropriate cable to inform you of a chassis intrusion.

Chassis Intrusion Pin Definitions (JL1)	
Pin#	Definition
1	Battery voltage
2	Intrusion signal

Wake-On-LAN

The Wake-On-LAN header is designated JWOL. See the table on the right for pin definitions. You must have a LAN card with a Wake-On-LAN connector and cable to use the Wake-On-LAN feature.

(Note: Wake-On-LAN from S3, S4, S5 are supported by LAN1. LAN2 supports Wake-On-LAN from S1 only.)

Wake-On-LAN Pin Definitions (JWOL)	
Pin#	Definition
1	+5V Standby
2	Ground
3	Wake-up

Wake-On-Ring

The Wake-On-Ring header is designated JWOR. This function allows your computer to receive and "wake-up" by an incoming call to the modem when in suspend state. See the table on the right for pin definitions. You must have a Wake-On-Ring card and cable to use this feature.

Wake-On-Ring Pin Definitions (JWOR)	
Pin#	Definition
1	Ground (Black)
2	Wake-up

Power Supply I²C Header

The JPI²C header is for I²C, which may be used to monitor the status of the power supply, fans and system temperature. See the table on the right for pin definitions.

I ² C Header Pin Definitions (JPI ² C)	
Pin#	Definition
1	Clock
2	Data
3	PWR Fail
4	Gnd
5	+3.3V

LAN1/2 (Ethernet Ports)



Two Gigabit Ethernet ports (designated LAN1 and LAN2) are located beside the VGA port. These Ethernet ports accept RJ45 type cables.

Power Supply Fail Alarm Reset Header

Connect JAR to the alarm reset button on your chassis (if available) or to a microswitch to allow you to turn off the alarm that sounds when a power supply module fails. See the table on the right for pin definitions.

Alarm Reset Header Pin Definitions (JAR)	
Pin#	Definition
1	Ground
2	Reset Signal

Power Supply Fail Alarm Header

Connect a cable from your power supply to JPWF to provide you with warning of a power supply failure. The warning signal is passed through the PWR_LED pin to indicate a power failure. See the table on the right for pin definitions.

Power Supply Fail Alarm Header Pin Definitions (JPWF)	
Pin#	Definition
1	P/S 1 Fail Signal
2	P/S 2 Fail Signal
3	P/S 3 Fail Signal
4	Reset (from MB)

Note: This feature is only available when using redundant power supplies.

Compact Flash Power Header

A Compact Flash Card Power header is located at JWF1. For the Compact Flash Card to work properly, you will first need to connect the device's power cable to JWF1 and correctly set the Compact Flash Jumper (JCF1).

Compact Flash Power Header Pin Definitions (JWF1)	
Pin#	Definition
1	+5V
2	Ground
3	Signal

GPIO

GPIO1 and GPIO2 (Serial General Purpose Input/Output) provide a bus between the SATA controller and the SATA drive backplane to provide SATA enclosure management functions. Connect the appropriate cables from the backplane to the GPIO1 and GPIO2 header(s) to utilize SATA management functions on your system.

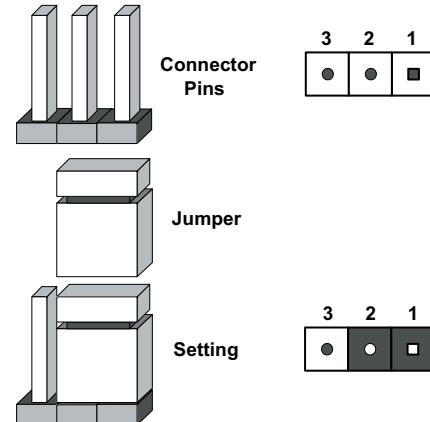
GPIO Header Pin Definitions (GPIO1, GPIO2)			
Pin#	Definition	Pin #	Definition
1	NC	2	NC
3	Ground	4	Data
5	Load	6	Ground
7	NC	8	NC

Note: NC indicates no connection.

5-9 Jumper Settings

Explanation of Jumpers

To modify the operation of the serverboard, jumpers can be used to choose between optional settings. Jumpers create shorts between two pins to change the function of the connector. Pin 1 is identified with a square solder pad on the printed circuit board. See the diagram at right for an example of jumping pins 1 and 2. Refer to the serverboard layout page for jumper locations.



Note: On two-pin jumpers, "Closed" means the jumper is on and "Open" means the jumper is off the pins.

CMOS Clear

JBT1 is used to clear CMOS and will also clear any passwords. Instead of pins, this jumper consists of contact pads to prevent accidentally clearing the contents of CMOS.

To clear CMOS,

- 1) First power down the system and unplug the power cord(s).
- 2) With the power disconnected, short the CMOS pads with a metal object such as a small screwdriver for at least four seconds.
- 3) Remove the screwdriver (or shorting device).
- 4) Reconnect the power cord(s) and power on the system.

Notes:

Do not use the PW_ON connector to clear CMOS.

The onboard battery does not need to be removed when clearing CMOS, however you must short JBT1 for at least four seconds.



JBT1 contact pads

I²C to PCI-X Enable/Disable

The JI²C1/2 pair of jumpers allows you to connect the System Management Bus to the PCI-X expansion slots. The default setting is disabled. Both connectors must be set the same (JI²C1 is for data and JI²C2 is for the clock). See the table on right for jumper settings.

I ² C to PCI-X Enable/Disable Jumper Settings (JI ² C1/2)	
Jumper Setting	Definition
Pins 1-2	Enabled
Pins 2-3	Disabled

I²C to PCI-E Enable/Disable

The JI²C3/4 pair of jumpers allows you to connect the System Management Bus to the PCI-Express expansion slots. The default setting is disabled. Both connectors must be set the same (JI²C3 is for data and JI²C4 is for the clock). See the table on right for jumper settings.

I ² C to PCI-E Enable/Disable Jumper Settings (JI ² C3/4)	
Jumper Setting	Definition
Pins 1-2	Enabled
Pins 2-3	Disabled

Watch Dog

JWD controls Watch Dog, a system monitor that takes action when a software application freezes the system. Jumping pins 1-2 will cause WD to reset the system if an application is hung up. Jumping pins 2-3 will generate a non-maskable interrupt signal for the application that is hung up. See the table on the right for jumper settings. Watch Dog must also be enabled in BIOS.

Watch Dog Jumper Settings (JWD)	
Jumper Setting	Definition
Pins 1-2	Reset
Pins 2-3	NMI
Open	Disabled

Note: When enabled, the user needs to write their own application software in order to disable the Watch Dog timer.

Compact Flash Master/Slave

The JCF1 jumper allows you to assign either master or slave status a compact flash card installed in IDE1. See the table on the right for jumper settings.

Compact Flash Master/Slave Jumper Settings (JCF1)	
Jumper Setting	Definition
Closed	Master
Open	Slave

PCI-X Slot Speed

Jumper JPXA1 on the H8DM3-2 is used to change the speed of PCI-X slots #1 & 2. Jumper JPXB1 is used to change the speed of PCI-X slot #3. See the tables on the right for jumper settings.

Note: JPXA1 controls the speed for PCI-X slots #1

and #2. JPXB1 controls the speed for PCI-X slot #3.

The default setting for both is Open (Auto).

PCI-X Slot Speed Jumper Settings (JPXA1/JPXB1)	
Jumper Setting	Definition
Open	Auto
Pins 1-2	PCI-X 66 MHz
Pins 2-3	PCI 66 MHz

VGA Enable/Disable

JPG1 allows you to enable or disable the VGA port. The default position is on pins 1 and 2 to enable VGA. See the table on the right for jumper settings.

VGA Enable/Disable Jumper Settings (JPG1)	
Jumper Setting	Definition
Pins 1-2	Enabled
Pins 2-3	Disabled

SAS RAID Select

JPS1 allows you to select the RAID firmware to use. SR RAID is the default. Selecting IT RAID requires you to flash firmware. See the table on the right for jumper settings.

SAS RAID Select Jumper Settings (JPS1)	
Jumper Setting	Definition
Open	IT RAID
Closed	SR RAID

Power Supply Fail Detect Enable/Disable

The system can notify you in the event of a power supply failure. This feature assumes that redundant power supply modules are installed in the chassis. If you only have a single power supply installed, you should disable this function with J3P to prevent false alarms. See the table on the right for jumper settings.

Power Supply Fail Detect Jumper Settings (J3P)	
Jumper Setting	Definition
Open	Disabled
Closed	Enabled

5-10 Onboard Indicators

LAN1/LAN2 LEDs

The Ethernet ports (located beside the VGA port) have two LEDs. On each Gb LAN port, one LED indicates activity when blinking while the other LED may be amber or off to indicate the speed of the connection. See the table on the right for the functions associated with the connection speed LED.

JLAN LED (Connection Speed Indicator)	
LED Color	Definition
Off	10/100 MHz
Amber	1 GHz

+5V LED

When illuminated, the DP2 LED indicates that +5V power from the power supply is being supplied to the serverboard. DP2 should normally be illuminated when the system is operating.

5-11 Floppy, IDE, SATA and SAS Drive Connections

Use the following information to connect the floppy and hard disk drive cables.

- The floppy disk drive cable has seven twisted wires.
- A red mark on a wire typically designates the location of pin 1.
- A single floppy disk drive ribbon cable has 34 wires and two connectors to provide for two floppy disk drives. The connector with twisted wires always connects to drive A, and the connector that does not have twisted wires always connects to drive B.
- The 80-wire ATA133 IDE hard disk drive cable that came with your system has two connectors to support two drives. This special cable should be used to take advantage of the speed this new technology offers. The blue connector connects to the onboard IDE connector interface and the other connector(s) to your hard drive(s). Consult the documentation that came with your disk drive for details on actual jumper locations and settings for the hard disk drive.

Floppy Connector

The floppy connector is located beside the IDE connector. See the table on the right for pin definitions.

Floppy Drive Connector Pin Definitions (Floppy)			
Pin#	Definition	Pin #	Definition
1	GND	2	FDHDIN
3	GND	4	Reserved
5	Key	6	FDDEDIN
7	GND	8	Index-
9	GND	10	Motor Enable
11	GND	12	Drive Select B-
13	GND	14	Drive Select A-
15	GND	16	Motor Enable
17	GND	18	DIR-
19	GND	20	STEP-
21	GND	22	Write Data-
23	GND	24	Write Gate-
25	GND	26	Track 00-
27	GND	28	Write Protect-
29	GND	30	Read Data-
31	GND	32	Side 1 Select-
33	GND	34	Diskette

IDE Connector

There are no jumpers to configure the onboard IDE#1 connector unless using it for a compact flash device. See the table on the right for pin definitions.

IDE Drive Connectors Pin Definitions (IDE#1)			
Pin#	Definition	Pin #	Definition
1	Reset IDE	2	Ground
3	Host Data 7	4	Host Data 8
5	Host Data 6	6	Host Data 9
7	Host Data 5	8	Host Data 10
9	Host Data 4	10	Host Data 11
11	Host Data 3	12	Host Data 12
13	Host Data 2	14	Host Data 13
15	Host Data 1	16	Host Data 14
17	Host Data 0	18	Host Data 15
19	Ground	20	Key
21	DRQ3	22	Ground
23	I/O Write	24	Ground
25	I/O Read	26	Ground
27	IOCHRDY	28	BALE
29	DACK3	30	Ground
31	IRQ14	32	IOCS16
33	Addr1	34	Ground
35	Addr0	36	Addr2
37	Chip Select 0	38	Chip Select 1
39	Activity	40	Ground

SATA Ports

There are no jumpers to configure the SATA ports, which are designated SATA0 through SATA5. See the table on the right for pin definitions.

SATA Drive Ports Pin Definitions (SATA0-SATA5)	
Pin #	Definition
1	Ground
2	TXP
3	TXN
4	Ground
5	RXN
6	RXP
7	Ground

SAS Ports

There are two SAS port connectors located near the IDE and floppy connectors. One is for the SAS0~3 ports and the other is for SAS4~7 ports. See the table on the right for pin definitions.

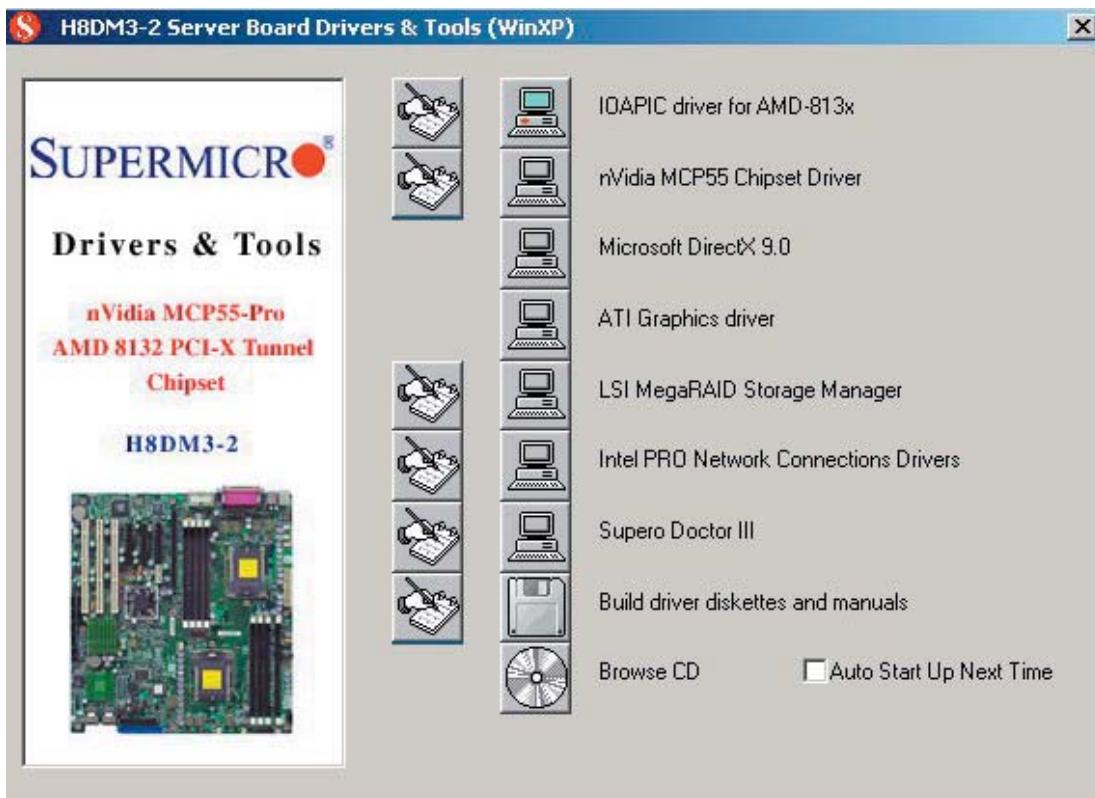
Note: SAS is enabled in BIOS (refer to Chapter 7). See LSI's SAS manual for details on creating and working with SAS RAID arrays. See the LSI SAS manual (included on the Supermicro CD) for SAS RAID set up instructions.

SAS Ports Pin Definitions (SAS0~3/SAS4~7)			
Pin#	Definition	Pin #	Definition
1	Rx0+	2	Rx0-
3	Rx1+	4	Rx1-
5	Rx2+	6	Rx2-
7	Rx3+	8	Rx3-
9	Tx3-	10	Tx3+
11	Tx2-	12	Tx2+
13	Tx1-	14	Tx1+
15	Tx0-	16	Tx0+

5-12 Installing Additional Drivers

The CD that came bundled with the system contains software drivers, some of which must be installed, such as the chipset driver. After inserting this CD into your CD-ROM drive, the display shown in Figure 5-7 should appear. (If this display does not appear, click on the My Computer icon and then on the icon representing your CD-ROM drive. Finally, double click on the S "Setup" icon.)

Figure 5-7. Driver/Tool Installation Display Screen



Click the icons showing a hand writing on paper to view the readme files for each item. Click the computer icons to the right of these items to install each item (from top to the bottom) one at a time. **After installing each item, you should reboot the system before moving on to the next item on the list.** The bottom icon with a CD on it allows you to view the entire contents of the CD.

Notes

Chapter 6

Advanced Chassis Setup

This chapter covers the steps required to install components and perform simple maintenance on the SC745TQ-R800 chassis. Following the component installation steps in the order given will eliminate most common problems. If some steps are unnecessary, skip ahead to the step that follows. Refer to Chapter 2 for instructions on installing the system as a 4U rackmount.

Tools Required

The only tool you will need is a Philips screwdriver.

6-1 Static-Sensitive Devices

Static electrical discharge can damage electronic components. To prevent damage to any printed circuit boards (PCBs), it is important to handle them very carefully. The following measures are generally sufficient to protect your equipment from static discharge.

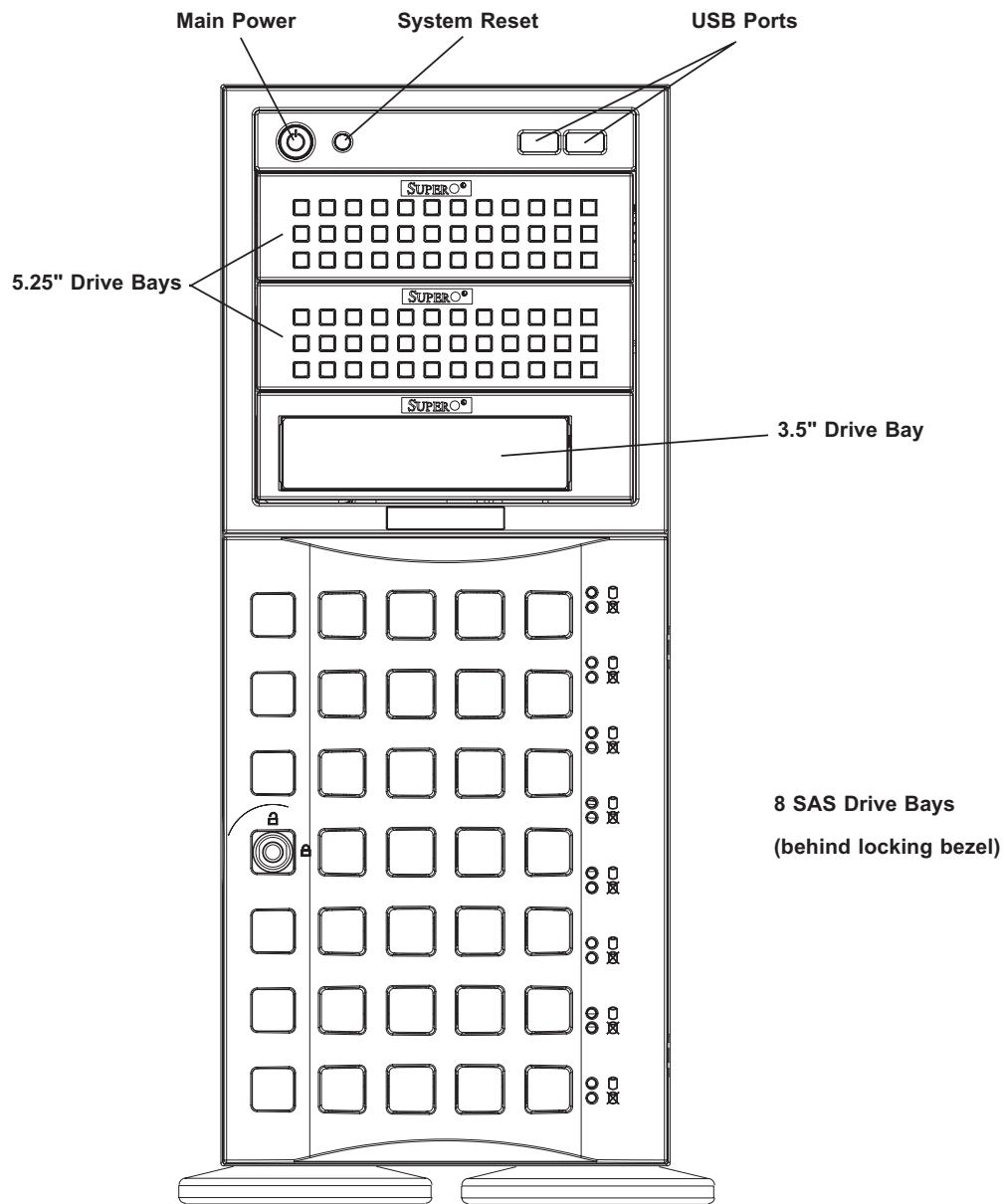
Precautions

- Use a grounded wrist strap designed to prevent static discharge.
- Touch a grounded metal object before removing any board from its antistatic bag.
- Handle a board by its edges only; do not touch its components, peripheral chips, memory modules or gold contacts.
- When handling chips or modules, avoid touching their pins.
- Put the serverboard, add-on cards and peripherals back into their antistatic bags when not in use.
- For grounding purposes, make sure your computer chassis provides excellent conductivity between the power supply, the case, the mounting fasteners and the serverboard.

Unpacking

The serverboard is shipped in antistatic packaging. When unpacking the board, make sure the person handling it is static protected.

Figure 6-1. Chassis Front View



6-2 Control Panel

The front control panel must be connected to the JF1 connector on the serverboard to provide you with system status and alarm indications. A ribbon cable has bundled these wires together to simplify this connection. Connect the cable from JF1 on the serverboard (making sure the red wire plugs into pin 1) to the appropriate connector on the front control panel PCB (printed circuit board). Pull all excess cabling over to the control panel side of the chassis. The LEDs on the control panel inform you of system status - see Figure 6-2 for details. See Chapter 5 for details on JF1.

Figure 6-2. Front Control Panel LEDs

Power		Indicates power is being supplied to the system.
HDD		Indicates IDE device and hard drive activity. On the SC745TQ-R800, this LED indicates SAS hard drive activity when flashing.
NIC1		Indicates network activity on LAN port 1.
NIC2		Indicates network activity on LAN port 2
Overheat/Fan Fail		When this LED flashes, it indicates a fan failure. When on continuously it indicates an overheat condition (see Chapter 3 for details).
Power Fail		Indicates a power supply failure.

6-3 System Fans

Three 8-cm chassis fans (located in the center of the chassis) provide cooling airflow while two 8-cm exhaust fans expel hot air from the chassis. The chassis is also fitted with an air shroud to concentrate the flow of cool air over the areas of highest generated heat. The fans should all be connected to headers on the serverboard (see Chapter 5). Each power supply module also has a fan.

Fan Failure

Under normal operation, all three chassis fans, both exhaust fans and the power supply fans run continuously. The chassis fans and the exhaust fans are hot-swappable and can be replaced without powering down the system.

Replacing Chassis Fans

1. Identifying the failed fan

To locate and replace a failed chassis fan, begin by removing the top/left chassis cover (see Chapter 2 for details on removing the cover). Locate the fan that has stopped working.

2. Removing a hot-plug fan housing

Depress the locking tab on the failed fan: on a chassis fan, push the tab on the side of the housing inward, on the exhaust fan push down on the colored tab. With the tab depressed, pull the unit straight out (see Figure 6-3). The wiring for these fans has been designed to detach automatically.

3. Installing a new system fan

Replace the failed fan with an identical one (see Appendix for part numbers). Install it in the same position and orientation as the one you removed; it should click into place when fully inserted. Check that the fan is working then replace the top/left side chassis panel.

Removing the air shroud

Under most circumstances you will not need to remove the air shroud to perform any service on the system. However, if you wish to temporarily remove it (the air shroud should always be in place when the system is operating), please follow this procedure.

Begin by depressing the tabs at the front and rear of the shroud to unlock it, then lift it up and out of the chassis (see Figure 6-4). To reinstall, simply position the air shroud in its proper place and push it in until you hear it click.

Figure 6-3. Removing a Chassis Fan

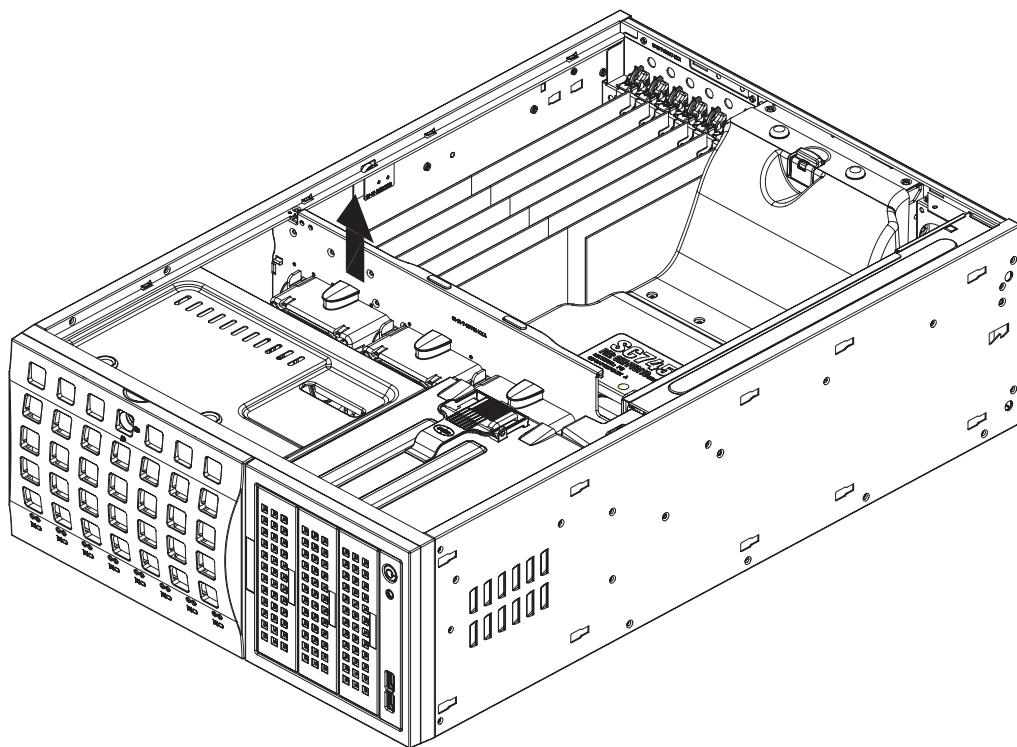
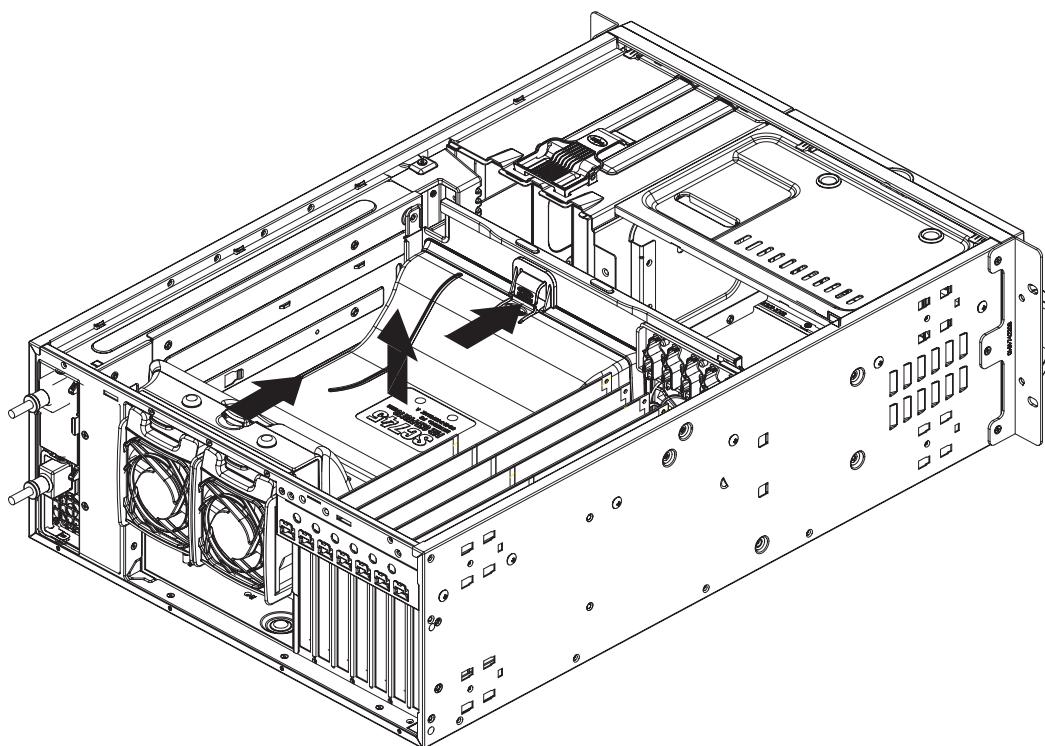


Figure 6-4. Removing the Air Shroud



6-4 Drive Bay Installation

SAS Drives

A total of eight SAS drives may be housed in the SC745TQ-R800 chassis. The drive IDs are preconfigured as 0 through 7 in order from bottom to top (or from left to right if rackmounted). A bezel covers the drive area but does not need to be removed to access the drives; simply swing open the bezel. If you wish to remove the bezel piece, push on the three tabs on the inside of the left lip of the front chassis cover. Then slightly swing out the same (left) side of the cover - about $\frac{1}{2}$ inch only. Remove by pushing on the open side of the cover to remove it from the chassis (do not try to swing or pull it straight out after opening the left side).



Regardless of how many SAS drives are installed, all drive carriers must remain in the drive bays to promote proper airflow.

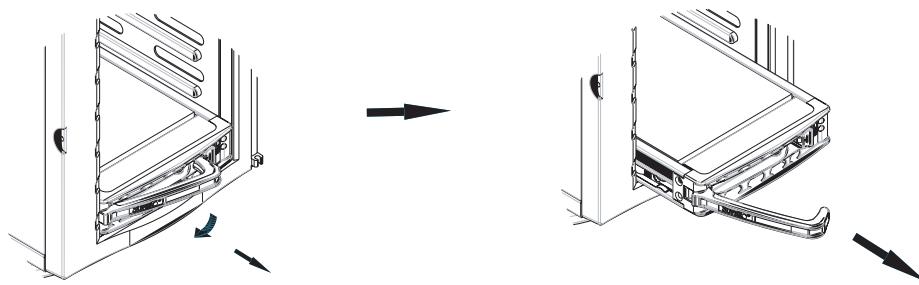
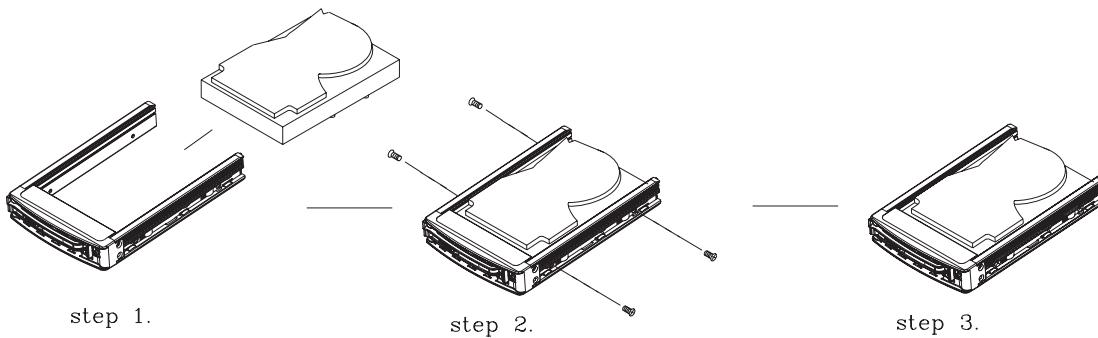
1. Installing/removing hot-swap SAS drives

The SAS drive carriers are all easily accessible at the front of the chassis. These drives are hot-swappable, meaning they can be removed and installed without powering down the system. To remove a carrier, first open the front bezel then push the release button located beside the drive LEDs. Swing the handle fully out and then use it to pull the unit straight out.

Note: Your operating system must have RAID support to enable the hot-swap capability of the SAS drives.

2. Mounting a SAS drive in a drive carrier

The SAS drives are mounted in drive carriers to simplify their installation and removal from the chassis. These carriers also work to promote proper airflow for the system. For this reason, even carriers without SAS drives must remain in the server. If you need to add a new SAS drive, insert the drive into the carrier with the printed circuit board side facing down so that the mounting holes align with those in the carrier. Secure the drive to the carrier with four screws (see Figure 6-6).

Figure 6-5. Removing a SAS Drive Carrier**Figure 6-6. Mounting a SAS Drive in a Carrier**

Important! Use extreme caution when working around the SAS backplane. Do not touch the backplane with any metal objects and make sure no ribbon cables touch the backplane or obstruct the airflow holes.

3. SAS backplane

The SAS drives plug into a SAS backplane. Two iPass cables (CBL-0119L-02) need to be connected from the serverboard to the appropriate connectors on the backplane to support the eight SAS six drives. You cannot cascade the SAS backplane.

Installing Components in the 5.25"/3.5" Drive Bays

1. Drive bay configuration

The 4021M-32R has two 5.25" and one 3.5" drive bays. Components such as an extra floppy drive, IDE hard drives or CD-ROM drives can be installed into these 5.25" drive bays.

2. Mounting components in the drive bays

First power down the system and then remove the top/left chassis cover to access the drive bays. With the cover off, remove the two or four screws that secure the drive carrier to the chassis (one side only) then push the entire empty drive carrier out from the back.

Adding a CD-ROM drive: remove the guide plates (one on each side) from the empty drive carrier and screw them into both sides of the CD-ROM drive using the holes provided. Then slide the CD-ROM into the bay and secure it to the chassis with the drive carrier screws you first removed. Attach the power and data cables to the drive. Replace the top/left chassis cover before restoring power to the system.

Adding an IDE or floppy drive: to add one of these drives, install it into one of the removed empty drive carriers with the printed circuit board side toward the carrier so that the drive's mounting holes align with those in the carrier. Secure the drive to the carrier with four screws then slide the assembly into the bay and secure it to the chassis with the drive carrier screws you first removed. Attach the power and data cables to the drive. Replace the top/left chassis cover before restoring power to the system.

Note: A red wire typically designates the location of pin 1. You should keep the drive carriers inserted in any unused drive bays to reduce EMI and noise and to facilitate the airflow inside the chassis.

6-5 Power Supply

The SuperServer 4021M-32R has a redundant 800 watt power supply consisting of two power modules. Each power supply module has an auto-switching capability, which enables it to automatically sense and operate at a 100V - 240V input voltage.

Power Supply Failure

If either of the two power supply modules fail, the other module will take the full load and allow the system to continue operation without interruption. The PWR Fail LED will illuminate and remain on until the failed unit has been replaced. Replacement units can be ordered directly from Supermicro (see contact information in the Preface). The hot-swap capability of the power supply modules allows you to replace the failed module without powering down the system.

Removing/Replacing the Power Supply

You do not need to shut down the system to replace a power supply unit. The redundant feature will keep the system up and running while you replace the failed hot-swap unit. Replace with the same model - (see Appendix D).

1. Removing the power supply

First unplug the power cord from the failed power supply unit. Then depress the locking tab on the power supply unit and pull the unit straight out by the handle.

2. Installing a new power supply

Replace the failed module with another power supply module (must be the exact same - refer to Appendix D for part number). Simply push the new power supply unit into the power bay until you hear a click. Finish by plugging the AC power cord back into the unit.

Notes

Chapter 7

BIOS

7-1 Introduction

This chapter describes the AMIBIOS™ Setup utility for the H8DM3-2. The AMI ROM BIOS is stored in a flash chip and can be easily upgraded using a floppy disk-based program.

Note: Due to periodic changes to the BIOS, some settings may have been added or deleted and might not yet be recorded in this manual. Please refer to the Manual Download area of our web site for any changes to BIOS that may not be reflected in this manual.

Starting the Setup Utility

To enter the BIOS Setup Utility, hit the <Delete> key while the system is booting-up. (In most cases, the <Delete> key is used to invoke the BIOS setup screen. There are a few cases when other keys are used, such as <F1>, <F2>, etc.) Each main BIOS menu option is described in this manual.

The Main BIOS screen has two main frames. The left frame displays all the options that can be configured. “Grayed-out” options cannot be configured. The right frame displays the key legend. Above the key legend is an area reserved for a text message. When an option is selected in the left frame, it is highlighted in white. Often a text message will accompany it. (Note that BIOS has default text messages built in. We retain the option to include, omit, or change any of these text messages.) Settings printed in **Bold** are the default values.

A "►" indicates a submenu. Highlighting such an item and pressing the <Enter> key will open the list of settings within that submenu.

The BIOS setup utility uses a key-based navigation system called hot keys. Most of these hot keys (<F1>, <F10>, <Enter>, <ESC>, <Arrow> keys, etc.) can be used at any time during the setup navigation process.

7-2 Main Menu

When you first enter AMI BIOS Setup Utility, you will see the Main Menu screen. You can always return to the Main Menu by selecting the **Main** tab on the top of the screen with the arrow keys.

The Main Menu screen provides you with a system overview, which includes the version, built date and ID of the AMIBIOS, the type, speed and number of the processors in the system and the amount of memory installed in the system.

System Time/System Date

You can edit this field to change the system time and date. Highlight *System Time* or *System Date* using the <Arrow> keys. Enter new values through the keyboard. Press the <Tab> key or the <Arrow> keys to move between fields. The date must be entered in DAY/MM/DD/YYYY format. The time is entered in HH:MM:SS format. Please note that time is in a 24-hour format. For example, 5:30 A.M. appears as 05:30:00 and 5:30 P.M. as 17:30:00.

7-3 Advanced Settings Menu

► Boot Features

Quick Boot

If Enabled, this option will skip certain tests during POST to reduce the time needed for the system to boot up. The options are **Enabled** and **Disabled**.

Quiet Boot

If **Disabled**, normal POST messages will be displayed on boot-up. If Enabled, this display the OEM logo instead of POST messages.

Add-On ROM Display Mode

Set this option to display add-on ROM (read-only memory) messages. The default setting is **Force BIOS**. Select Force BIOS to allow the computer system to force a third party BIOS to display during system boot. Select Keep Current to allow the computer system to display the BIOS information during system boot. The options are **Force BIOS** and **Keep Current**.

Boot up Num-Lock

Set this value to allow the Number Lock setting to be modified during boot up. The options are **On** and Off.

PS/2 Mouse Support

Set this value to modify support for a PS/2 mouse. The options are **Auto**, Enabled and Disabled.

Wait for 'F1' If Error

Select Enable to activate the Wait for F1 if Error function. The options are **Enabled** and Disabled.

Hit 'DEL' Message Display

Select Enabled to display message to hit the DEL key to enter Setup. The options are **Enabled** and Disabled.

Interrupt 19 Capture

Select Enabled to allow ROMs to trap Interrupt 19. The options are **Enabled** and Disabled.

OS Installation

Change this setting if using a 64-bit Linux operating system. The available options are **Other** and **Linux**.

ACPI Configuration

ACPI Version Features

Use this setting to determine which ACPI version to use. Options are **ACPI v1.0**, ACPI v2.0 and ACPI v3.0.

ACPI APIC Support

Determines whether to include the ACPI APIC table pointer in the RSDT pointer list. The available options are **Enabled** and **Disabled**.

AMI OEMB Table

Determines whether to include the AMI APIC table pointer in the RSDT pointer list. The available options are **Enabled** and **Disabled**.

Headless Mode

Use this setting to Enable or **Disable** headless operation mode through ACPI.

MCP55 ACPI HPET Table

Use this setting to either **Enable** or Disable the MCP55 ACPI HPET table.

Power Configuration

Power Button Mode

Allows the user to change the function of the power button. Options are **On/Off** and Suspend.

Restore on AC Power Loss

This setting allows you to choose how the system will react when power returns after an unexpected loss of power. The options are Power Off, Power On and **Last State**.

Watch Dog Timer

This setting is used to Enable or **Disable** the Watch Dog Timer function. It must be used in conjunction with the Watch Dog jumper (see Chapter 2 for details).

MPS Configuration

MPS Revision

This setting allows the user to select the MPS revision level. The options are 1.1 and **1.4**.

Smbios Configuration

Smbios Smi Support

This setting allows SMI wrapper support for PnP function 50h-54h. The options are **Enabled** and Disabled.

► CPU Configuration

MThe submenu lists CPU information and the following settings:

GART Error Reporting

This setting is used for testing only (setting should be **disabled**).

Power Now

This setting is used to Enable or **Disable** the AMD Power Now feature.

Thermal Throttling

This setting is used to Enable or **Disable** Thermal Throttling.

► Floppy/IDE/SATA Configuration

Floppy A

Move the cursor to these fields via up and down <arrow> keys to select the floppy type. The options are **Disabled**, 360 KB 5 1/4", 1.2 MB 5 1/4", 720 KB 3 1/2", **1.44 MB 3 1/2"**, and 2.88 MB 3 1/2".

Floppy B

Move the cursor to these fields via up and down <arrow> keys to select the floppy type. The options are **Disabled**, 360 KB 5 1/4", 1.2 MB 5 1/4", 720 KB 3 1/2", 1.44 MB 3 1/2", and 2.88 MB 3 1/2".

Onboard Floppy Controller

Use this setting to **Enable** or **Disable** the onboard floppy controller.

Onboard IDE Controller

There is a single floppy controller on the motherboard, which may be **Enabled** or **Disabled** with this setting.

Serial ATA Devices

This setting is used to determine if SATA drives will be used and how many. Options are **Disabled**, **Device 0**, **Device 0/1** and **Device 0/1/2**.

nVidia RAID Function

This setting is used to Enable or **Disable** the nVidia ROM.

Primary IDE Master/Slave

Highlight one of the items above and press <Enter> to access the submenu for that item.

Type

Select the type of device connected to the system. The options are Not Installed, **Auto**, CDROM and ARMD.

LBA/Large Mode

LBA (Logical Block Addressing) is a method of addressing data on a disk drive. The options are Disabled and **Auto**.

Block (Multi-Sector Transfer)

Block mode boosts IDE drive performance by increasing the amount of data transferred. Only 512 bytes of data can be transferred per interrupt if block mode is not used. Block mode allows transfers of up to 64 KB per interrupt. Select "Disabled" to allow the data to be transferred from and to the device one sector at a time. Select "Auto" to allow the data transfer from and to the device occur multiple sectors at a time if the device supports it. The options are **Auto** and Disabled.

PIO Mode

PIO (Programmable I/O) mode programs timing cycles between the IDE drive and the programmable IDE controller. As the PIO mode increases, the cycle time decreases. The options are **Auto**, 0, 1, 2, 3, and 4. Select Auto to allow AMI BIOS to auto detect the PIO mode. Use this value if the IDE disk drive support cannot be determined. Select 0 to allow AMI BIOS to use PIO mode 0. It has a data transfer rate of 3.3 MBs. Select 1 to allow AMI BIOS to use PIO mode 1. It has a data transfer rate of 5.2 MBs. Select 2 to allow AMI BIOS to use PIO mode 2. It has a data transfer rate of 8.3 MBs. Select 3 to allow AMI BIOS to use PIO mode 3. It has a data transfer rate of 11.1 MBs. Select 4 to allow AMI BIOS to use PIO mode 4. It has a data transfer rate of 16.6 MBs. This setting generally works with all hard disk drives manufactured after 1999. For other disk drives, such as IDE CD-ROM drives, check the specifications of the drive.

DMA Mode

Selects the DMA Mode. Options are **Auto**, SWDMA0, SWDMA1, SWDMA2, MWDMA0, MWDMA1, MWDMA2, UDMA0, UDMA1, UDMA2, UDMA3, UDMA4 and UDMA5. (SWDMA=Single Word DMA, MWDMA=Multi Word DMA, UDMA=UltraDMA.)

S.M.A.R.T.

Self-Monitoring Analysis and Reporting Technology (SMART) can help predict impending drive failures. Select "Auto" to allow BIOS to auto detect hard disk drive support. Select "Disabled" to prevent AMI BIOS from using the S.M.A.R.T. Select "Enabled" to allow AMI BIOS to use the S.M.A.R.T. to support hard drive disk. The options are Disabled, Enabled, and **Auto**.

32-Bit Data Transfer

Select "Enabled" to activate the function of 32-Bit data transfer. Select "Disabled" to deactivate the function. The options are Enabled and **Disabled**.

Serial ATA0/1/2 Primary/Secondary Channel

Highlight one of the items above and press <Enter> to access the submenu for that item. If a drive is present, information on that drive will be displayed here.

LBA/Large Mode

LBA (Logical Block Addressing) is a method of addressing data on a disk drive. The options are Disabled and **Auto**.

Block (Multi-Sector Transfer)

Block mode boosts IDE drive performance by increasing the amount of data transferred. Only 512 bytes of data can be transferred per interrupt if block mode is not used. Block mode allows transfers of up to 64 KB per interrupt. Select "Disabled" to allow the data to be transferred from and to the device one sector at a time. Select "Auto" to allow the data transfer from and to the device occur multiple sectors at a time if the device supports it. The options are **Auto** and Disabled.

PIO Mode

PIO (Programmable I/O) mode programs timing cycles between the IDE drive and the programmable IDE controller. As the PIO mode increases, the cycle time decreases. The options are **Auto**, 0, 1, 2, 3, and 4. Select Auto to allow AMI BIOS to auto detect the PIO mode. Use this value if the IDE disk drive support

cannot be determined. Select 0 to allow AMI BIOS to use PIO mode 0. It has a data transfer rate of 3.3 MBs. Select 1 to allow AMI BIOS to use PIO mode 1. It has a data transfer rate of 5.2 MBs. Select 2 to allow AMI BIOS to use PIO mode 2. It has a data transfer rate of 8.3 MBs. Select 3 to allow AMI BIOS to use PIO mode 3. It has a data transfer rate of 11.1 MBs. Select 4 to allow AMI BIOS to use PIO mode 4. It has a data transfer rate of 16.6 MBs. This setting generally works with all hard disk drives manufactured after 1999. For other disk drives, such as IDE CD-ROM drives, check the specifications of the drive.

DMA Mode

Selects the DMA Mode. Options are **Auto**, SWDMA0, SWDMA1, SWDMA2, MWDMA0, MWDMA1, MWDMA2, UDMA0, UDMA1, UDMA2, UDMA3, UDMA4 and UDMA5. (SWDMA=Single Word DMA, MWDMA=Multi Word DMA, UDMA=UltraDMA.)

S.M.A.R.T.

Self-Monitoring Analysis and Reporting Technology (SMART) can help predict impending drive failures. Select "Auto" to allow BIOS to auto detect hard disk drive support. Select "Disabled" to prevent AMI BIOS from using the S.M.A.R.T. Select "Enabled" to allow AMI BIOS to use the S.M.A.R.T. to support hard drive disk. The options are Disabled, Enabled, and **Auto**.

32-Bit Data Transfer

Select "Enabled" to activate the function of 32-Bit data transfer. Select "Disabled" to deactivate the function. The options are Enabled and **Disabled**.

Hard Disk Write Protect

Select Enabled to enable the function of Hard Disk Write Protect to prevent data from being written to HDD. The options are Enabled or **Disabled**.

IDE Detect Time Out (Sec)

This feature allows the user to set the time-out value for detecting ATA, ATA PI devices installed in the system. The options are 0 (sec), 5, 10, 15, 20, 25, 30 and **35**.

ATA(PI) 80Pin Cable Detection

This setting allows AMI BIOS to auto-detect the 80-Pin ATA(PI) cable. The options are **Host & Device**, Host and Device.

► PCI/PnP Configuration

Clear NVRAM

Select Yes to clear NVRAM during boot-up. The options are Yes and **No**.

Plug & Play OS

Select Yes to allow the OS to configure Plug & Play devices. (This is not required for system boot if your system has an OS that supports Plug & Play.) Select **No** to allow AMIBIOS to configure all devices in the system.

PCI Latency Timer

This option sets the latency of all PCI devices on the PCI bus. Select a value to set the PCI latency in PCI clock cycles. Options are 32, **64**, 96, 128, 160, 192, 224 and 248.

Allocate IRQ to PCI VGA

Set this value to allow or restrict the system from giving the VGA adapter card an interrupt address. The options are **Yes** and No.

Palette Snooping

Select "Enabled" to inform the PCI devices that an ISA graphics device is installed in the system in order for the graphics card to function properly. The options are **Enabled** and **Disabled**.

PCI IDE BusMaster

Set this value to allow or prevent the use of PCI IDE busmastering. Select "Enabled" to allow AMI BIOS to use PCI busmaster for reading and writing to IDE drives. The options are **Disabled** and **Enabled**.

Offboard PCI/ISA IDE Card

This option allows the user to assign a PCI slot number to an Off-board PCI/ISA IDE card in order for it to function properly. The options are **Auto**, PCI Slot1, PCI Slot2, PCI Slot3, PCI Slot4, PCI Slot5, and PCI Slot6.

IRQ3/IRQ4/IRQ5/IRQ7/IRQ9/IRQ10/IRQ11/IRQ14/IRQ15

This feature specifies the availability of an IRQ to be used by a PCI/PnP device. Select Reserved for the IRQ to be used by a Legacy ISA device. The options are **Available** and **Reserved**.

DMA Channel 0/1/3/5/6/7

This feature specifies the availability of a DMA channel. The options are **Available** and **Reserved**.

Reserved Memory Size

This setting sets the size of the memory block to reserve for Legacy ISA devices. The options are **Disabled**, 16k, 32k and 64k.

Onboard SAS Controller

This setting is used to **Enable** or **Disable** the onboard SAS controller.

► Super IO Configuration

Serial Port1 Address

This option specifies the base I/O port address and Interrupt Request address of serial port 1. Select "Disabled" to prevent the serial port from accessing any system resources. When this option is set to *Disabled*, the serial port physically becomes unavailable. Select "3F8/IRQ4" to allow the serial port to use 3F8 as its I/O port address and IRQ 4 for the interrupt address. The options are **Disabled**, **3F8/IRQ4**, **3E8/IRQ4** and **2E8/IRQ3**.

Serial Port2 Address

This option specifies the base I/O port address and Interrupt Request address of serial port 2. Select "Disabled" to prevent the serial port from accessing any system resources. When this option is set to "Disabled", the serial port physically becomes unavailable. Select "2F8/IRQ3" to allow the serial port to use 2F8 as its I/O port address and IRQ 3 for the interrupt address. The options are **Disabled**, **2F8/IRQ3**, **3E8/IRQ4** and **2E8/IRQ3**.

Serial Port 2 Mode

Tells BIOS which mode to select for serial port 2. The options are **Normal**, **IrDA** and **ASKIR**.

Parallel Port Address

This option specifies the I/O address used by the parallel port. Select **Disabled** to prevent the parallel port from accessing any system resources. When the value of this option is set to **Disabled**, the printer port becomes unavailable. Select **378** to

allow the parallel port to use 378 as its I/O port address. The majority of parallel ports on computer systems use IRQ7 and I/O Port 378H as the standard setting. Select 278 to allow the parallel port to use 278 as its I/O port address. Select 3BC to allow the parallel port to use 3BC as its I/O port address.

Parallel Port Mode

Specify the parallel port mode. The options are **Normal**, Bi-directional, EPP and ECP.

Parallel Port IRQ

Select the IRQ (interrupt request) for the parallel port. The options are IRQ5 and **IRQ7**.

- ▶ **Chipset Configuration**
- ▶ **NorthBridge Configuration**
- ▶ **Memory Configuration**

Memclock Mode

This setting determines how the memory clock is set. **Auto** has the memory clock by code and **Manual** and **Limit** allow the user to set a standard value.

MCT Timing Mode

Sets the timing mode for memory. Options are **Auto** and **Manual**.

Bank Interleaving

Select **Auto** to automatically enable interleaving-memory scheme when this function is supported by the processor. The options are **Auto** and **Disabled**.

Enable Clock to All DIMMs

Use this setting to enable unused clocks to all DIMMSs, even if some DIMM slots are unpopulated. Options are **Enabled** and **Disabled**.

MemClk Tristate C3/ALTVID

Use this setting to **Enable** or **Disable** memory clock tristate during C3 and ALTVID.

CS Sparing Enable

This setting will reserve a spare memory rank in each node when enabled. Options are **Enable** and **Disable**.

Memory Hole Remapping

When "Enabled", this feature enables hardware memory remapping around the memory hole. Options are **Enabled** and **Disabled**.

► ECC Configuration

DRAM ECC Enable

DRAM ECC allows hardware to report and correct memory errors automatically. Options are **Enabled** and **Disabled**.

4-Bit ECC Mode

Allows the user to enable 4-bit ECC mode (also known as ECC Chipkill). Options are **Enabled** and **Disabled**.

DRAM Scrub Redirect

Allows system to correct DRAM ECC errors immediately, even with background scrubbing on. Options are **Enabled** and **Disabled**.

DRAM BG Scrub

Corrects memory errors so later reads are correct. Options are **Disabled** and various times in nanoseconds and microseconds.

L2 Cache BG Scrub

Allows L2 cache RAM to be corrected when idle. Options are **Disabled** and various times in nanoseconds and microseconds.

Data Cache BG Scrub

Allows L1 cache RAM to be corrected when idle. Options are **Disabled** and various times in nanoseconds and microseconds.

Power Down Control

Allows DIMMs to enter power down mode by deasserting the clock enable signal when DIMMs are not in use. Options are **Auto** and **Disabled**.

Alternate VID

Specify the alternate VID while in low power states. Options are **Auto** and various voltages from .800V to 1.050V in increments of .025V.

► SouthBridge Configuration

CPU/LDT Spread Spectrum

Enables spread spectrum for the CPU/LDT. Options are **Center Spread**, Down Spread or Disabled.

PCIE Spread Spectrum

Allows you to **Enable** or Disable spread spectrum for PCI-Express..

SATA Spread Spectrum

Enables spread spectrum for the SATA. Options are **Enabled** and Disabled.

Primary Graphics Adapter

Options are **PCI Express --> PCI** and **PCI --> PCI Express**.

USB 1.1 Controller

Enable or disable the USB 1.1 controller.

USB 2.0 Controller

Enable or disable the USB 2.0 controller.

MAC0 LAN0

Settings are **Auto** and Disabled for MAC0 LAN0.

MAC1 LAN1

Settings are **Auto** and Disabled for MAC1 LAN1.

Legacy USB Support

Select "Enabled" to enable the support for USB Legacy. Disable Legacy support if there are no USB devices installed in the system. "Auto" disabled Legacy support if no USB devices are connected. The options are **Disabled**, **Enabled** and **Auto**.

USB 2.0 Controller Mode

Select the controller mode for your USB ports. Options are **HiSpeed** and **FullSpeed**. (HiSpeed=480 Mbps, FullSpeed=12 Mbps).

BIOS EHCI Hand-Off

Enable or **Disable** a workaround for OS's without EHCI hand-off support.

► **Event Log Configuration**

View Event Log

Highlight this item and press <Enter> to view the contents of the event log.

Mark All Events as Read

Highlight this item and press <Enter> to mark all events as read.

Clear Event Log

Select Yes and press <Enter> to clear all event logs. The options are Yes and No to verify.

► **PCI Express Configuration**

Active State Power Management

Used to **Enable** or **Disable** the PCI-Express L0 and L1 link power states.

► **Remote Access Configuration**

Remote Access

Allows you to **Enable** or **Disable** remote access.

► System Health Monitor

CPU Overheat Alarm

Use the "+" and "-" keys to set the CPU temperature threshold to between 65° and 90° C. When this threshold is exceeded, the overheat LED on the chassis will light up and an alarm will sound. The LED and alarm will turn off once the CPU temperature has dropped to 5 degrees below the threshold set. The default setting is **72° C**.

The submenu includes monitor displays for the following information:

CPU1 Temperature, CPU2 Temperature (for dual CPU systems), System Temperature, VCore1, VCore2 (for dual CPU systems), 3.3V, +5Vin, +12Vin, 5V stby and battery voltage.

► System Fan Monitor

Fan Speed Control Modes

This feature allows the user to determine how the system will control the speed of the onboard fans. Select "Workstation" if your system is used as a Workstation. Select "Server" if your system is used as a Server. Select "Disable" to disable the fan speed control function to allow the onboard fans to continuously run at full speed (12V). The options are **1) Disabled (Full Speed)** **2) Server Mode** and **3) Workstation Mode**.

FAN1 Speed through FAN8 Reading

The speeds of the onboard fans (in rpm) are displayed here.

7-4 Boot Menu

This feature allows the user to configure the following items:

► Boot Device Priority

This feature allows the user to prioritize the boot sequence from the available devices.

► Removable Drives

This feature allows the user to specify the Boot sequence from available removable drives.

7-5 Security Menu

AMI BIOS provides a Supervisor and a User password. If you use both passwords, the Supervisor password must be set first.

Change Supervisor Password

Select this option and press <Enter> to access the sub menu, and then type in the password.

Change User Password

Select this option and press <Enter> to access the sub menu, and then type in the password.

Boot Sector Virus Protection

This option is near the bottom of the Security Setup screen. Select "Disabled" to deactivate the Boot Sector Virus Protection. Select "Enabled" to enable boot sector protection. When "Enabled", AMI BIOS displays a warning when any program (or virus) issues a Disk Format command or attempts to write to the boot sector of the hard disk drive. The options are **Enabled** and **Disabled**.

7-6 Exit Menu

Select the Exit tab from AMI BIOS Setup Utility screen to enter the Exit BIOS Setup screen.

Save Changes and Exit

When you have completed the system configuration changes, select this option to leave BIOS Setup and reboot the computer, so the new system configuration parameters can take effect. Select Save Changes and Exit from the Exit menu and press <Enter>.

Discard Changes and Exit

Select this option to quit BIOS Setup without making any permanent changes to the system configuration and reboot the computer. Select Discard Changes and Exit from the Exit menu and press <Enter>.

Discard Changes

Select this option and press <Enter> to discard all the changes and return to AMI BIOS Utility Program.

Load Optimal Defaults

To set this feature, select Load Optimal Defaults from the Exit menu and press <Enter>. Then Select "OK" to allow BIOS to automatically load the Optimal Defaults as the BIOS Settings. The Optimal settings are designed for maximum system performance, but may not work best for all computer applications.

Load Fail-Safe Defaults

To set this feature, select Load Fail-Safe Defaults from the Exit menu and press <Enter>. The Fail-Safe settings are designed for maximum system stability, but not maximum performance.

Notes

Appendix A

BIOS Error Beep Codes

During the POST (Power-On Self-Test) routines, which are performed each time the system is powered on, errors may occur.

Non-fatal errors are those which, in most cases, allow the system to continue the boot-up process. The error messages normally appear on the screen.

Fatal errors are those which will not allow the system to continue the boot-up procedure. If a fatal error occurs, you should consult with your system manufacturer for possible repairs.

These fatal errors are usually communicated through a series of audible beeps. The numbers on the fatal error list, on the following page, correspond to the number of beeps for the corresponding error. All errors listed, with the exception of Beep Code 8, are fatal errors.

POST codes may be read on the debug LEDs located beside the LAN port on the serverboard backplane. See the description of the Debug LEDs (LED1 and LED2) in Chapter 5.

A-1 AMIBIOS Error Beep Codes

Beep Code	Error Message	Description
1 beep	Refresh	Circuits have been reset. (Ready to power up.)
5 short, 1 long	Memory error	No memory detected in system
8 beeps	Display memory read/write error	Video adapter missing or with faulty memory

Notes

Appendix B

BIOS POST Checkpoint Codes

When AMIBIOS performs the Power On Self Test, it writes checkpoint codes to I/O port 0080h. If the computer cannot complete the boot process, diagnostic equipment can be attached to the computer to read I/O port 0080h.

B-1 Uncompressed Initialization Codes

The uncompressed initialization checkpoint codes are listed in order of execution:

Checkpoint	Code Description
D0h	The NMI is disabled. Power on delay is starting. Next, the initialization code checksum will be verified.
D1h	Initializing the DMA controller, performing the keyboard controller BAT test, starting memory refresh and entering 4 GB flat mode next.
D3h	Starting memory sizing next.
D4h	Returning to real mode. Executing any OEM patches and setting the Stack next.
D5h	Passing control to the uncompressed code in shadow RAM at E000:0000h. The initialization code is copied to segment 0 and control will be transferred to segment 0.

B-2 Bootblock Recovery Codes

The bootblock recovery checkpoint codes are listed in order of execution:

Checkpoint	Code Description
E0h	The onboard floppy controller if available is initialized. Next, beginning the base 512 KB memory test.
E1h	Initializing the interrupt vector table next.
E2h	Initializing the DMA and Interrupt controllers next.
E6h	Enabling the floppy drive controller and Timer IRQs. Enabling internal cache memory.
Edh	Initializing the floppy drive.
Eeh	Looking for a floppy diskette in drive A:. Reading the first sector of the diskette.
Efh	A read error occurred while reading the floppy drive in drive A:.
F0h	Next, searching for the AMIBOOT.ROM file in the root directory.
F1h	The AMIBOOT.ROM file is not in the root directory.
F2h	Next, reading and analyzing the floppy diskette FAT to find the clusters occupied by the AMIBOOT.ROM file.
F3h	Next, reading the AMIBOOT.ROM file, cluster by cluster.
F4h	The AMIBOOT.ROM file is not the correct size.
F5h	Next, disabling internal cache memory.
FBh	Next, detecting the type of flash ROM.
FCh	Next, erasing the flash ROM.
FDh	Next, programming the flash ROM.
FFh	Flash ROM programming was successful. Next, restarting the system BIOS.

B-3 Uncompressed Initialization Codes

The following runtime checkpoint codes are listed in order of execution.
These codes are uncompressed in F0000h shadow RAM.

Checkpoint	Code Description
03h	The NMI is disabled. Next, checking for a soft reset or a power on condition.
05h	The BIOS stack has been built. Next, disabling cache memory.
06h	Uncompressing the POST code next.
07h	Next, initializing the CPU and the CPU data area.
08h	The CMOS checksum calculation is done next.
0Ah	The CMOS checksum calculation is done. Initializing the CMOS status register for date and time next.
0Bh	The CMOS status register is initialized. Next, performing any required initialization before the keyboard BAT command is issued.
0Ch	The keyboard controller input buffer is free. Next, issuing the BAT command to the keyboard controller.
0Eh	The keyboard controller BAT command result has been verified. Next, performing any necessary initialization after the keyboard controller BAT command test.
0Fh	The initialization after the keyboard controller BAT command test is done. The keyboard command byte is written next.
10h	The keyboard controller command byte is written. Next, issuing the Pin 23 and 24 blocking and unblocking command.
11h	Next, checking if <End or <Ins> keys were pressed during power on. Initializing CMOS RAM if the Initialize CMOS RAM in every boot AMIBIOS POST option was set in AMIBCP or the <End> key was pressed.
12h	Next, disabling DMA controllers 1 and 2 and interrupt controllers 1 and 2.
13h	The video display has been disabled. Port B has been initialized. Next, initializing the chipset.
14h	The 8254 timer test will begin next.
19h	Next, programming the flash ROM.
1Ah	The memory refresh line is toggling. Checking the 15 second on/off time next.
2Bh	Passing control to the video ROM to perform any required configuration before the video ROM test.
2Ch	All necessary processing before passing control to the video ROM is done. Looking for the video ROM next and passing control to it.
2Dh	The video ROM has returned control to BIOS POST. Performing any required processing after the video ROM had control
23h	Reading the 8042 input port and disabling the MEGAKEY Green PC feature next. Making the BIOS code segment writable and performing any necessary configuration before initializing the interrupt vectors.
24h	The configuration required before interrupt vector initialization has completed. Interrupt vector initialization is about to begin.

Checkpoint	Code Description
25h	Interrupt vector initialization is done. Clearing the password if the POST DIAG switch is on.
27h	Any initialization before setting video mode will be done next.
28h	Initialization before setting the video mode is complete. Configuring the monochrome mode and color mode settings next.
2Ah	Bus initialization system, static, output devices will be done next, if present. See the last page for additional information.
2Eh	Completed post-video ROM test processing. If the EGA/VGA controller is not found, performing the display memory read/write test next.
2Fh	The EGA/VGA controller was not found. The display memory read/write test is about to begin.
30h	The display memory read/write test passed. Look for retrace checking next.
31h	The display memory read/write test or retrace checking failed. Performing the alternate display memory read/write test next.
32h	The alternate display memory read/write test passed. Looking for alternate display retrace checking next.
34h	Video display checking is over. Setting the display mode next.
37h	The display mode is set. Displaying the power on message next.
38h	Initializing the bus input, IPL, general devices next, if present. See the last page of this chapter for additional information.
39h	Displaying bus initialization error messages. See the last page of this chapter for additional information.
3Ah	The new cursor position has been read and saved. Displaying the Hit message next.
3Bh	The Hit message is displayed. The protected mode memory test is about to start.
40h	Preparing the descriptor tables next.
42h	The descriptor tables are prepared. Entering protected mode for the memory test next.
43h	Entered protected mode. Enabling interrupts for diagnostics mode next.
44h	Interrupts enabled if the diagnostics switch is on. Initializing data to check memory wraparound at 0:0 next.
45h	Data initialized. Checking for memory wraparound at 0:0 and finding the total system memory size next.
46h	The memory wraparound test is done. Memory size calculation has been done. Writing patterns to test memory next.
47h	The memory pattern has been written to extended memory. Writing patterns to the base 640 KB memory next.
48h	Patterns written in base memory. Determining the amount of memory below 1 MB next.
49h	The amount of memory below 1 MB has been found and verified.
4Bh	The amount of memory above 1 MB has been found and verified. Checking for a soft reset and clearing the memory below 1 MB for the soft reset next. If this is a power on situation, going to checkpoint 4Eh next.

Checkpoint	Code Description
4Ch	The memory below 1 MB has been cleared via a soft reset. Clearing the memory above 1 MB next.
4Dh	The memory above 1 MB has been cleared via a soft reset. Saving the memory size next. Going to checkpoint 52h next.
4Eh	The memory test started, but not as the result of a soft reset. Displaying the first 64 KB memory size next.
4Fh	The memory size display has started. The display is updated during the memory test. Performing the sequential and random memory test next.
50h	The memory below 1 MB has been tested and initialized. Adjusting the displayed memory size for relocation and shadowing next.
51h	The memory size display was adjusted for relocation and shadowing.
52h	The memory above 1 MB has been tested and initialized. Saving the memory size information next.
53h	The memory size information and the CPU registers are saved. Entering real mode next.
54h	Shutdown was successful. The CPU is in real mode. Disabling the Gate A20 line, parity, and the NMI next.
57h	The A20 address line, parity, and the NMI are disabled. Adjusting the memory size depending on relocation and shadowing next.
58h	The memory size was adjusted for relocation and shadowing. Clearing the Hit message next.
59h	The Hit message is cleared. The <WAIT...> message is displayed. Starting the DMA and interrupt controller test next.
60h	The DMA page register test passed. Performing the DMA Controller 1 base register test next.
62h	The DMA controller 1 base register test passed. Performing the DMA controller 2 base register test next.
65h	The DMA controller 2 base register test passed. Programming DMA controllers 1 and 2 next.
66h	Completed programming DMA controllers 1 and 2. Initializing the 8259 interrupt controller next.
67h	Completed 8259 interrupt controller initialization.
7Fh	Extended NMI source enabling is in progress.
80h	The keyboard test has started. Clearing the output buffer and checking for stuck keys. Issuing the keyboard reset command next.
81h	A keyboard reset error or stuck key was found. Issuing the keyboard controller interface test command next.
82h	The keyboard controller interface test completed. Writing the command byte and initializing the circular buffer next.
83h	The command byte was written and global data initialization has completed. Checking for a locked key next.
84h	Locked key checking is over. Checking for a memory size mismatch with CMOS RAM data next.
85h	The memory size check is done. Displaying a soft error and checking for a password or bypassing WINBIOS Setup next.

Checkpoint	Code Description
86h	The password was checked. Performing any required programming before WINBIOS Setup next.
87h	The programming before WINBIOS Setup has completed. Uncompressing the WINBIOS Setup code and executing the AMIBIOS Setup or WINBIOS Setup utility next.
88h	Returned from WINBIOS Setup and cleared the screen. Performing any necessary programming after WINBIOS Setup next.
89h	The programming after WINBIOS Setup has completed. Displaying the power on screen message next.
8Ch	Programming the WINBIOS Setup options next.
8Dh	The WINBIOS Setup options are programmed. Resetting the hard disk controller next.
8Fh	The hard disk controller has been reset. Configuring the floppy drive controller next.
91h	The floppy drive controller has been configured. Configuring the hard disk drive controller next.
95h	Initializing the bus option ROMs from C800 next. See the last page of this chapter for additional information.
96h	Initializing before passing control to the adaptor ROM at C800.
97h	Initialization before the C800 adaptor ROM gains control has completed. The adaptor ROM check is next.
98h	The adaptor ROM had control and has now returned control to BIOS POST. Performing any required processing after the option ROM returned control.
99h	Any initialization required after the option ROM test has completed. Configuring the timer data area and printer base address next.
9Ah	Set the timer and printer base addresses. Setting the RS-232 base address next.
9Bh	Returned after setting the RS-232 base address. Performing any required initialization before the Coprocessor test next.
9Ch	Required initialization before the Coprocessor test is over. Initializing the Coprocessor next.
9Dh	Coprocessor initialized. Performing any required initialization after the Coprocessor test next.
9Eh	Initialization after the Coprocessor test is complete. Checking the extended keyboard, keyboard ID, and Num Lock key next. Issuing the keyboard ID command next.
A2h	Displaying any soft errors next.
A3h	The soft error display has completed. Setting the keyboard typematic rate next.
A4h	The keyboard typematic rate is set. Programming the memory wait states next.
A5h	Memory wait state programming is over. Clearing the screen and enabling parity and the NMI next.
A7h	NMI and parity enabled. Performing any initialization required before passing control to the adaptor ROM at E000 next.
A8h	Initialization before passing control to the adaptor ROM at E000h completed. Passing control to the adaptor ROM at E000h next.

Checkpoint	Code Description
A9h	Returned from adaptor ROM at E000h control. Performing any initialization required after the E000 option ROM had control next.
Aah	Initialization after E000 option ROM control has completed. Displaying the system configuration next.
Abh	Uncompressing the DMI data and executing DMI POST initialization next.
B0h	The system configuration is displayed.
B1h	Copying any code to specific areas.
00h	Code copying to specific areas is done. Passing control to INT 19h boot loader next.

Notes

Appendix C

System Specifications

Processors

Single or dual AMD Opteron 2000 series (Socket F) type processors

Note: Please refer to our web site for a complete listing of supported processors.

Chipset

nVidia MCP55 Pro and AMD-8132 chipset

BIOS

8 Mb AMI® Flash ROM

Memory Capacity

Eight 240-pin DIMM sockets supporting up to 32 GB of registered ECC DDR2-667/533/400 SDRAM.

Note: See the memory section in Chapter 5 for details.

Serial Attached SCSI (SAS) Controller

LSI 1068E controller for eight-port SAS (RAID 0, 1, 10 and JBOD supported
- RAID 5 supported with optional I-Button installed)

Serial ATA (SATA) Controller

On-chip controller for six-port Serial ATA (RAID 0, 1, 0+1, 5 and JBOD supported)

SAS Drive Bays

Eight (8) hot-swap drive bays to house eight (8) standard SAS drives

Peripheral Drive Bays

One (1) 3.5" drive bay

Two (2) 5.25" drive bays

Expansion Slots

Two PCI-Express x8 slots, one PCI-Express x4 slot, one 64-bit 133 MHz PCI-X slot and two 64-bit 133/100 MHz PCI-X slots (all low-profile cards)

Serverboard

H8DM3-2 (Extended ATX form factor)
Dimensions: 12 x 13.05 in (305 x 331 mm)

Chassis

SC745TQ-R800, tower/4U rackmount
Dimensions (as tower): (WxHxD) 7 x 19 x 27 in. (178 x 483 x 686 mm)

Weight

Gross (Bare Bone): 70 lbs. (31.8 kg.)

System Cooling

Three (3) 8-cm system cooling fans
Two (2) 8-cm rear exhaust fans
One (1) air shroud for tower/4U chassis

System Input Requirements

AC Input Voltage: 100-240V AC auto-range
Rated Input Current: 12A max.
Rated Input Frequency: 50 to 60 Hz

Power Supply

Rated Output Power: 800W (Part# SP801-1R)
Rated Output Voltages: +12V (66A), +5Vsb (4A)

BTU Rating

3921 BTUs/hr (for rated output power of 800W)

Operating Environment

Operating Temperature: 10° to 35° C (50° to 95° F)
Non-operating Temperature: -40° to 70° C (-40° to 158° F)
Operating Relative Humidity: 8% to 90% (non-condensing)
Non-operating Relative Humidity: 5 to 95% (non-condensing)

Regulatory Compliance

Electromagnetic Emissions:

FCC Class A, EN 55022 Class A, EN 61000-3-2/-3-3, CISPR 22 Class A

Electromagnetic Immunity:

EN 55024/CISPR 24, (EN 61000-4-2, EN 61000-4-3, EN 61000-4-4,
EN 61000-4-5, EN 61000-4-6, EN 61000-4-8, EN 61000-4-11)

Safety:

EN 60950/IEC 60950-Compliant, UL Listed (USA), CUL Listed (Canada), TUV
Certified (Germany), CE Marking (Europe)

Notes